## Subject: [RFC][PATCH 0/4] Object creation with a specified id Posted by Nadia Derbey on Mon, 10 Mar 2008 13:50:54 GMT

View Forum Message <> Reply to Message

A couple of weeks ago, a discussion has started after Pierre's proposal for a new syscall to change an ipc id (see thread http://lkml.org/lkml/2008/1/29/209).

Oren's suggestion was to force an object's id during its creation, rather than 1. create it, 2. change its id.

So here is an implementation of what Oren has suggested.

2 new files are defined under /proc/self:

- . next\_ipcid --> next id to use for ipc object creation
- . next\_pids --> next upid nr(s) to use for next task to be forked (see patch #2 for more details).

When one of these files (or both of them) is filled, a structure pointed to by the calling task struct is filled with these ids.

Then, when the object is created, the id(s) present in that structure are used, instead of the default ones.

The patches are against 2.6.25-rc3-mm1, in the following order:

[PATCH 1/4] adds the procfs facility for next ipc to be created.

[PATCH 2/4] adds the proofs facility for next task to be forked.

[PATCH 3/4] makes use of the specified id (if any) to allocate the new IPC object (changes the ipc\_addid() path).

[PATCH 4/4] uses the specified id(s) (if any) to set the upid nr(s) for a newly allocated process (changes the alloc\_pid()/alloc\_pidmap() paths).

Any comment and/or suggestions are welcome.

Cc-ing Pavel and Sukadev, since they are the pid namespace authors.

Regards, Nadia	
Containers	mailing list
Containers	@lists.linux-foundation.org
https://lists	.linux-foundation.org/mailman/listinfo/containers

## Subject: [RFC][PATCH 1/4] Provide a new procfs interface to set next ipc id Posted by Nadia Derbey on Mon, 10 Mar 2008 13:50:55 GMT

View Forum Message <> Reply to Message

## [PATCH 01/04]

This patch proposes the procfs facilities needed to feed the id for the next ipc object to be allocated.

```
if an
echo XX > /proc/self/next_ipcid
is issued, next ipc object to be created will have XX as its id.
Signed-off-by: Nadia Derbey <Nadia.Derbey@bull.net>
fs/proc/base.c
                 include/linux/sched.h |
                      3 ++
include/linux/sysids.h | 20 ++++++++++
kernel/Makefile
                    2 -
5 files changed, 121 insertions(+), 1 deletion(-)
Index: linux-2.6.25-rc3-mm1/include/linux/sysids.h
--- /dev/null 1970-01-01 00:00:00.000000000 +0000
+++ linux-2.6.25-rc3-mm1/include/linux/sysids.h 2008-03-10 11:39:10.000000000 +0100
@ @ -0,0 +1,20 @ @
+/*
+ * include/linux/sysids.h
+ * Definitions to support object creation with predefined id.
+ */
+#ifndef LINUX SYSIDS H
+#define _LINUX_SYSIDS_H
+#define SYS_ID_IPC 1
+struct sys_id {
+ int flag; /* which id should be set */
+ int ipc;
+};
+extern int ipc_set_nextid(struct task_struct *, int id);
+#endif /* _LINUX_SYSIDS_H */
Index: linux-2.6.25-rc3-mm1/include/linux/sched.h
```

```
--- linux-2.6.25-rc3-mm1.orig/include/linux/sched.h 2008-03-10 09:18:46.000000000 +0100
+++ linux-2.6.25-rc3-mm1/include/linux/sched.h 2008-03-10 09:28:30.00000000 +0100
@ @ -87,6 +87,7 @ @ struct sched_param {
#include linux/task_io_accounting.h>
#include linux/kobject.h>
#include linux/latencytop.h>
+#include ux/sysids.h>
#include <asm/processor.h>
@ @ -1261,6 +1262,8 @ @ struct task struct {
 int latency_record_count;
 struct latency_record latency_record[LT_SAVECOUNT];
#endif
+ /* Id to assign to the next resource to be created */
+ struct sys_id *next_id;
};
Index: linux-2.6.25-rc3-mm1/fs/proc/base.c
--- linux-2.6.25-rc3-mm1.orig/fs/proc/base.c 2008-03-10 09:19:39.000000000 +0100
+++ linux-2.6.25-rc3-mm1/fs/proc/base.c 2008-03-10 11:22:20.000000000 +0100
@@ -76,6 +76,7 @@
#include linux/oom.h>
#include linux/elf.h>
#include linux/pid namespace.h>
+#include linux/ctype.h>
#include "internal.h"
/* NOTE:
@@ -1080,6 +1081,69 @@ static const struct file_operations proc
#endif
+static ssize_t next_ipcid_read(struct file *file, char __user *buf,
   size_t count, loff_t *ppos)
+{
+ struct task struct *task;
+ char buffer[PROC NUMBUF];
+ size t len;
+ struct sys_id *sid;
+ int next_ipcid;
+ task = get_proc_task(file->f_path.dentry->d_inode);
+ if (!task)
+ return -ESRCH;
```

```
+
+ sid = task->next id;
+ next_ipcid = (sid) ? ((sid->flag & SYS_ID_IPC) ? sid->ipc : -1)
+ :-1;
+ put_task_struct(task);
+ len = snprintf(buffer, sizeof(buffer), "%i\n", next_ipcid);
+ return simple read from buffer(buf, count, ppos, buffer, len);
+}
+static ssize_t next_ipcid_write(struct file *file, const char __user *buf,
   size_t count, loff_t *ppos)
+{
+ struct inode *inode = file->f_path.dentry->d_inode;
+ char buffer[PROC_NUMBUF], *end;
+ int next_ipcid;
+ int rc;
+ if (pid_task(proc_pid(inode), PIDTYPE_PID) != current)
+ return -EPERM;
+ memset(buffer, 0, sizeof(buffer));
+ if (count > sizeof(buffer) - 1)
+ count = sizeof(buffer) - 1;
+ if (copy_from_user(buffer, buf, count))
+ return -EFAULT;
+ next_ipcid = simple_strtol(buffer, &end, 0);
+ if (next ipcid < 0 || end == buffer)
+ return -EINVAL;
+ while (isspace(*end))
+ end++;
+ rc = ipc_set_nextid(current, next_ipcid);
+ if (rc)
+ return rc;
+ if (end - buffer == 0)
+ return -EIO;
+ return end - buffer;
+}
+static const struct file_operations proc_next_ipcid_operations = {
+ .read = next ipcid read,
+ .write = next ipcid write,
```

```
+};
#ifdef CONFIG_SCHED_DEBUG
 * Print out various scheduling related per-task fields:
@ @ -2391.6 +2455.7 @ @ static const struct pid entry tgid base
#ifdef CONFIG_TASK_IO_ACCOUNTING
 INF("io", S IRUGO, pid io accounting),
#endif
+ REG("next_ipcid", S_IRUGO|S_IWUSR, next_ipcid),
static int proc_tgid_base_readdir(struct file * filp,
@ @ -2716,6 +2781,7 @ @ static const struct pid_entry tid_base_s
#ifdef CONFIG_FAULT_INJECTION
 REG("make-it-fail", S IRUGOIS IWUSR, fault inject),
#endif
+ REG("next_ipcid", S_IRUGO|S_IWUSR, next_ipcid),
};
static int proc tid base readdir(struct file * filp,
Index: linux-2.6.25-rc3-mm1/kernel/Makefile
_____
--- linux-2.6.25-rc3-mm1.orig/kernel/Makefile 2008-03-10 09:19:01.000000000 +0100
+++ linux-2.6.25-rc3-mm1/kernel/Makefile 2008-03-10 09:41:27.000000000 +0100
@ @ -9,7 +9,7 @ @ obj-y = sched.o fork.o exec_domain.o
   rcupdate.o extable.o params.o posix-timers.o \
   kthread.o wait.o kfifo.o sys ni.o posix-cpu-timers.o mutex.o \
   hrtimer.o rwsem.o nsproxy.o srcu.o semaphore.o \
   notifier.o ksysfs.o pm gos params.o
   notifier.o ksysfs.o pm_qos_params.o set_nextid.o
obj-$(CONFIG_SYSCTL_SYSCALL_CHECK) += sysctl_check.o
obj-$(CONFIG_STACKTRACE) += stacktrace.o
Index: linux-2.6.25-rc3-mm1/kernel/set nextid.c
_____
--- /dev/null 1970-01-01 00:00:00.000000000 +0000
+++ linux-2.6.25-rc3-mm1/kernel/set nextid.c 2008-03-10 10:09:47.000000000 +0100
@@ -0.0 +1.31 @@
+/*
+ * linux/kernel/set_nextid.c
+ * Provide the XXX_set_nextid() routines (called from fs/proc/base.c).
+ * They allow to specify the id for the next resource to be allocated,
+ * instead of letting the allocator set it for us.
+ */
```

```
+#include linux/sched.h>
+
+int ipc_set_nextid(struct task_struct *task, int id)
+{
+ struct sys_id *sid;
+ sid = task->next id;
+ if (!sid) {
+ sid = kzalloc(sizeof(*sid), GFP KERNEL);
+ if (!sid)
+ return -ENOMEM;
+ task->next_id = sid;
+ }
+ sid > ipc = id;
+ sid->flag |= SYS ID IPC;
+ return 0;
+}
```

Containers mailing list Containers@lists.linux-foundation.org https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: [RFC][PATCH 2/4] Provide a new procfs interface to set next upid nr(s) Posted by Nadia Derbey on Mon, 10 Mar 2008 13:50:56 GMT View Forum Message <> Reply to Message

[PATCH 02/04]

This patch proposes the procfs facilities needed to feed the id(s) for the next task to be forked.

say n is the number of pids to be provided through procfs:

if an echo "n X0 X1 ... X<n-1>" > /proc/self/next\_pids is issued, the next task to be forked will have its upid nrs set as follows (say it is forked in a pid ns of level L):

level upid nr

```
L ----> X0
L - i ----> Xi
L - n + 1 --> X<n-1>
Then, for levels L-n down to level 0, the pids will be left to the kernel
choice.
Signed-off-by: Nadia Derbey <Nadia.Derbey@bull.net>
fs/proc/base.c
                  | 74 +++++++++++++++++++
include/linux/sysids.h | 36 ++++++++
3 files changed, 254 insertions(+), 3 deletions(-)
Index: linux-2.6.25-rc3-mm1/include/linux/sysids.h
--- linux-2.6.25-rc3-mm1.orig/include/linux/sysids.h 2008-03-10 11:39:10.000000000 +0100
+++ linux-2.6.25-rc3-mm1/include/linux/sysids.h 2008-03-10 12:49:27.000000000 +0100
@@ -9,12 +9,46 @@
#define _LINUX_SYSIDS_H
#define SYS_ID_IPC 1
+#define SYS ID PID 2
+#define NPIDS SMALL
                          32
+#define NPIDS PER BLOCK ((unsigned int)(PAGE SIZE / sizeof(pid t)))
+/* access the pids "array" with this macro */
+#define PID_AT(pi, i) \
+ ((pi)->blocks[(i) / NPIDS_PER_BLOCK][(i) % NPIDS_PER_BLOCK])
+
+ * The next process to be created is associated to a set of upid nrs: one for
+ * each pid namespace level that process belongs to.
+ * upid nrs from level 0 up to level <npids - 1> will be automatically
+ * allocated.
+ * upid nr for level npids will be set to blocks[0][0]
+ * upid nr for level <npids + i> will be set to PID_AT(pids, i);
+struct pid_list {
+ int npids;
+ pid_t small_block[NPIDS_SMALL];
+ int nblocks;
```

+ pid t \*blocks[0];

```
+};
struct sys_id {
 int flag; /* which id should be set */
- int ipc;
+ struct {
+ int ipc;
+ struct pid_list *pids;
+ } ids;
};
+#define ipc_id ids.ipc
+#define pid_ids ids.pids
+extern void pids_free(struct pid_list *);
extern int ipc set nextid(struct task struct *, int id);
+extern ssize_t pid_get_nextids(struct task_struct *, char *);
+extern ssize_t pid_set_nextids(struct task_struct *, char *);
#endif /* _LINUX_SYSIDS_H */
Index: linux-2.6.25-rc3-mm1/fs/proc/base.c
--- linux-2.6.25-rc3-mm1.orig/fs/proc/base.c 2008-03-10 11:22:20.000000000 +0100
+++ linux-2.6.25-rc3-mm1/fs/proc/base.c 2008-03-10 12:27:34.000000000 +0100
@@ -1095,7 +1095,7 @@ static ssize t next ipcid read(struct fi
 return -ESRCH;
 sid = task->next id;
- next_ipcid = (sid) ? ((sid->flag & SYS_ID_IPC) ? sid->ipc : -1)
+ next ipcid = (sid) ? ((sid->flag & SYS ID IPC) ? sid->ipc id : -1)
  : -1;
 put_task_struct(task);
@@ -1144,6 +1144,76 @@ static const struct file_operations proc
};
+static ssize_t next_pids_read(struct file *file, char __user *buf,
   size_t count, loff_t *ppos)
+{
+ struct task_struct *task;
+ char *page;
+ ssize_t length;
+ task = get_proc_task(file->f_path.dentry->d_inode);
+ if (!task)
+ return -ESRCH;
```

```
+
+ if (count > PROC_BLOCK_SIZE)
+ count = PROC_BLOCK_SIZE;
+ length = -ENOMEM;
+ page = (char *) __get_free_page(GFP_TEMPORARY);
+ if (!page)
+ goto out;
+ length = pid get nextids(task, (char *) page);
+ if (length >= 0)
+ length = simple read from buffer(buf, count, ppos,
    (char *)page, length);
+ free_page((unsigned long) page);
+out:
+ put_task_struct(task);
+ return length;
+}
+static ssize_t next_pids_write(struct file *file, const char __user *buf,
   size t count, loff t *ppos)
+{
+ struct inode *inode = file->f_path.dentry->d_inode;
+ char *page;
+ ssize_t length;
+ if (current != pid_task(proc_pid(inode), PIDTYPE_PID))
+ return -EPERM;
+ if (count >= PAGE SIZE)
+ count = PAGE_SIZE - 1;
+ \text{ if (*ppos != 0) } \{
+ /* No partial writes. */
+ return -EINVAL;
+ page = (char *)__get_free_page(GFP_TEMPORARY);
+ if (!page)
+ return -ENOMEM;
+ length = -EFAULT;
+ if (copy_from_user(page, buf, count))
+ goto out_free_page;
+ page[count] = '\0';
+ length = pid_set_nextids(current, page);
+ if (!length)
+ length = count;
```

```
+out_free_page:
+ free_page((unsigned long) page);
+ return length;
+}
+
+static const struct file operations proc next pids operations = {
+ .read = next_pids_read,
+ .write = next pids write,
+};
+
#ifdef CONFIG_SCHED_DEBUG
 * Print out various scheduling related per-task fields:
@ @ -2456,6 +2526,7 @ @ static const struct pid_entry tgid_base_
 INF("io", S IRUGO, pid io accounting),
#endif
 REG("next_ipcid", S_IRUGO|S_IWUSR, next_ipcid),
+ REG("next_pids", S_IRUGO|S_IWUSR, next_pids),
};
static int proc_tgid_base_readdir(struct file * filp,
@ @ -2782,6 +2853,7 @ @ static const struct pid_entry tid_base_s
 REG("make-it-fail", S_IRUGO|S_IWUSR, fault_inject),
#endif
 REG("next_ipcid", S_IRUGO|S_IWUSR, next_ipcid),
+ REG("next_pids", S_IRUGO|S_IWUSR, next_pids),
};
static int proc tid base readdir(struct file * filp,
Index: linux-2.6.25-rc3-mm1/kernel/set nextid.c
--- linux-2.6.25-rc3-mm1.orig/kernel/set_nextid.c 2008-03-10 10:09:47.000000000 +0100
+++ linux-2.6.25-rc3-mm1/kernel/set nextid.c 2008-03-10 12:47:30.000000000 +0100
@@ -8,8 +8,59 @@
 */
#include linux/sched.h>
+#include linux/string.h>
+extern int pid_max;
+
+
+static struct pid_list *pids_alloc(int idsetsize)
+{
```

```
+ struct pid_list *pids;
+ int nblocks;
+ int i;
+
+ nblocks = (idsetsize + NPIDS_PER_BLOCK - 1) / NPIDS_PER_BLOCK;
+ BUG_ON(nblocks < 1);
+ pids = kmalloc(sizeof(*pids) + nblocks * sizeof(pid_t *), GFP_KERNEL);
+ if (!pids)
+ return NULL:
+ pids->npids = idsetsize;
+ pids->nblocks = nblocks;
+
+ if (idsetsize <= NPIDS_SMALL)
+ pids->blocks[0] = pids->small_block;
+ else {
+ for (i = 0; i < nblocks; i++) {
+ pid_t *b;
+ b = (void *) __get_free_page(GFP_KERNEL);
+ if (!b)
+ goto out_undo_partial_alloc;
 pids->blocks[i] = b;
+ }
+ }
+ return pids;
+out_undo_partial_alloc:
+ while (--i >= 0)
+ free page((unsigned long)pids->blocks[i]);
+ kfree(pids);
+ return NULL;
+}
+void pids_free(struct pid_list *pids)
+{
+ if (pids->blocks[0] != pids->small_block) {
+ int i:
+ for (i = 0; i < pids->nblocks; i++)
+ free_page((unsigned long)pids->blocks[i]);
+ }
+ kfree(pids);
+}
+
int ipc_set_nextid(struct task_struct *task, int id)
@ @ -23,9 +74,103 @ @ int ipc set nextid(struct task struct *t
```

```
task->next_id = sid;
 }
sid->ipc = id;
+ sid > ipc id = id:
 sid->flag |= SYS_ID_IPC;
 return 0;
}
+ssize_t pid_get_nextids(struct task_struct *task, char *buffer)
+ ssize_t count = 0;
+ struct sys_id *sid;
+ char *bufptr = buffer;
+ int i;
+ sid = task->next_id;
+ if (!sid)
+ return sprintf(buffer, "-1");
+ if (!(sid->flag & SYS ID PID))
+ return sprintf(buffer, "-1");
+ count = sprintf(&bufptr[count], "%d ", sid->pid_ids->npids);
+ for (i = 0; i < sid->pid_ids->npids - 1; i++)
+ count += sprintf(&bufptr[count], "%d",
   PID AT(sid->pid ids, i));
+ count += sprintf(&bufptr[count], "%d", PID_AT(sid->pid_ids, i));
+ return count;
+}
+
+ * Parses a line written to /proc/self/next_pids.
+ * this line has the following format:
+ * npids pid0 .... pidx
+ * with x = npids - 1
+ */
+ssize_t pid_set_nextids(struct task_struct *task, char *buffer)
+ char *token, *end, *out = buffer;
+ struct sys_id *sid;
+ struct pid_list *pids;
+ int npids, i;
+ ssize trc;
```

```
+
+ rc = -EINVAL;
+ token = strsep(&out, " ");
+ if (!token)
+ goto out;
+ npids = simple_strtol(token, &end, 0);
+ if (*end)
+ goto out;
+ if (npids <= 0 || npids > pid_max)
+ goto out;
+
+ rc = -ENOMEM;
+ pids = pids_alloc(npids);
+ if (!pids)
+ goto out;
+ rc = -EINVAL;
+ i = 0;
+ while ((token = strsep(&out, " ")) != NULL && i < npids) {
+ pid t pid;
+ if (!*token)
+ goto out_free;
+ pid = simple_strtol(token, &end, 0);
+ if ((*end && *end != '\n') || end == token || pid < 0)
+ goto out free;
+ PID_AT(pids, i) = pid;
+ i++;
+ }
+ if (i != npids)
+ /* Not enough pids compared to npids */
+ goto out_free;
+ sid = current->next_id;
+ if (!sid) {
+ rc = -ENOMEM;
+ sid = kzalloc(sizeof(*sid), GFP_KERNEL);
+ if (!sid)
+ goto out_free;
+ current->next_id = sid;
+ } else if (sid->flag & SYS_ID_PID)
+ kfree(sid->pid_ids);
+ rc = 0;
```

```
+ sid->pid ids = pids;
+ sid->flag |= SYS ID PID;
+out:
+ return rc;
+out_free:
+ pids_free(pids);
+ return rc;
+}
Containers mailing list
Containers@lists.linux-foundation.org
https://lists.linux-foundation.org/mailman/listinfo/containers
Subject: [RFC][PATCH 3/4] IPC: use the target ID specified in procfs
Posted by Nadia Derbey on Mon, 10 Mar 2008 13:50:57 GMT
View Forum Message <> Reply to Message
[PATCH 03/04]
This patch makes use of the target id specified by a previous write into
/proc/self/next ipcid as the id to use to allocate the next IPC object.
Signed-off-by: Nadia Derbey <Nadia.Derbey@bull.net>
1 file changed, 31 insertions(+), 8 deletions(-)
Index: linux-2.6.25-rc3-mm1/ipc/util.c
--- linux-2.6.25-rc3-mm1.orig/jpc/util.c 2008-03-10 13:10:33.000000000 +0100
+++ linux-2.6.25-rc3-mm1/ipc/util.c 2008-03-10 13:11:24.000000000 +0100
@@ -35,6 +35,7 @@
#include linux/rwsem.h>
#include linux/memory.h>
#include linux/ipc_namespace.h>
+#include ux/sysids.h>
#include <asm/unistd.h>
@ @ -267,20 +268,42 @ @ int ipc addid(struct ipc ids* ids, struc
 if (ids->in use >= size)
 return -ENOSPC;
```

- err = idr\_get\_new(&ids->ipcs\_idr, new, &id);

```
- if (err)
- return err;
+ /* If there is a target id specified, try to use it */
+ if (current->next_id && (current->next_id->flag & SYS_ID_IPC)) {
+ int new_id = current->next_id->ipc_id;
+ int new_lid = new_id % SEQ_MULTIPLIER;
+
+ if (new id !=
     (new_lid + (new_id / SEQ_MULTIPLIER) * SEQ_MULTIPLIER))
  return -EINVAL;
+ err = idr get new above(&ids->ipcs idr, new, new lid, &id);
+ if (err)
+ return err;
+ if (id != new_lid) {
+ idr_remove(&ids->ipcs_idr, id);
+ return -EBUSY;
+ }
+
+ new->id = new id;
+ new->seq = new_id / SEQ_MULTIPLIER;
+ current->next id->flag &= ~SYS ID IPC;
+ } else {
+ err = idr_get_new(&ids->ipcs_idr, new, &id);
+ if (err)
+ return err;
+ new->seq = ids->seq++;
+ if (ids->seq > ids->seq max)
+ ids->seq=0;
+ new->id = ipc buildid(id, new->seq);
+ }
 ids->in_use++;
 new->cuid = new->uid = current->euid;
 new->gid = new->cgid = current->egid;
- new->seq = ids->seq++;
- if(ids->seq > ids->seq max)
- ids->seq=0;
- new->id = ipc_buildid(id, new->seq);
 spin_lock_init(&new->lock);
 new->deleted = 0:
 rcu_read_lock();
```

Containers mailing list Containers@lists.linux-foundation.org https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: [RFC][PATCH 4/4] PID: use the target ID specified in procfs Posted by Nadia Derbey on Mon, 10 Mar 2008 13:50:58 GMT View Forum Message <> Reply to Message

[PATCH 04/04]

This patch makes use of the target ids specified by a previous write to /proc/self/next\_pids as the ids to use to allocate the next upid nrs. Upper levels upid nrs that are not specified in next\_pids file are left to the kernel choice.

Signed-off-by: Nadia Derbey <Nadia.Derbey@bull.net> kernel/fork.c | 5 ++-2 files changed, 73 insertions(+), 12 deletions(-) Index: linux-2.6.25-rc3-mm1/kernel/pid.c \_\_\_\_\_ --- linux-2.6.25-rc3-mm1.orig/kernel/pid.c 2008-03-10 09:19:02.000000000 +0100 +++ linux-2.6.25-rc3-mm1/kernel/pid.c 2008-03-10 13:45:52.000000000 +0100 @ @ -122,14 +122,26 @ @ static void free\_pidmap(struct upid \*upi atomic inc(&map->nr free); } -static int alloc\_pidmap(struct pid\_namespace \*pid\_ns) +static int alloc pidmap(struct pid namespace \*pid ns, struct pid list \*pid l, + int level) int i, offset, max\_scan, pid, last = pid\_ns->last\_pid; struct pidmap \*map; - pid = last + 1; - if (pid  $\geq$  pid max) pid = RESERVED PIDS; + if (!pid\_l) { + pid = last + 1; + if (pid >= pid\_max) + pid = RESERVED\_PIDS; + } else {

+ /\*

```
* There's a target pid, so use it instead
+ BUG_ON(level < 0);
+ pid = PID_AT(pid_I, level);
+ if (pid >= pid_max)
+ return -EINVAL;
+ }
 offset = pid & BITS_PER_PAGE_MASK;
 map = &pid_ns->pidmap[pid/BITS_PER_PAGE];
 max_scan = (pid_max + BITS_PER_PAGE - 1)/BITS_PER_PAGE - !offset;
@ @ -153,9 +165,16 @ @ static int alloc pidmap(struct pid names
  do {
   if (!test_and_set_bit(offset, map->page)) {
   atomic_dec(&map->nr_free);
   pid_ns->last_pid = pid;
    if (!pid I)
    pid_ns->last_pid = pid;
+
    else
    pid_ns->last_pid = max(last,
       pid);
   return pid;
   }
  if (pid_l)
   /* Target pid is already in use */
    return -EBUSY;
   offset = find_next_offset(map, offset);
   pid = mk_pid(pid_ns, map, offset);
@ @ -179,7 +198,7 @ @ static int alloc_pidmap(struct pid_names
 pid = mk_pid(pid_ns, map, offset);
- return -1;
+ return -ENOMEM;
}
int next_pidmap(struct pid_namespace *pid_ns, int last)
@ @ -250,14 +269,55 @ @ struct pid *alloc_pid(struct pid_namespa
 int i, nr;
 struct pid namespace *tmp;
 struct upid *upid;
+ struct pid_list *pid_I = NULL;
+ int rel_level = -1;
+
+ /*
+ * If there is a list of upid nrs specified, use it instead of letting
+ * the kernel chose them for us.
```

```
+ */
+ if (current->next_id && (current->next_id->flag & SYS_ID_PID)) {
+ pid_I = current->next_id->pid_ids;
+ BUG_ON(!pid_l);
+ rel_level = pid_l->npids - 1;
+ if (rel_level > ns->level) {
+ pid = ERR_PTR(-EINVAL);
+ goto out;
+ }
+ }
 pid = kmem cache alloc(ns->pid cachep, GFP KERNEL);
- if (!pid)
+ if (!pid) {
+ pid = ERR_PTR(-ENOMEM);
  goto out;
+ }
 tmp = ns;
- for (i = ns->level; i >= 0; i--) {
nr = alloc_pidmap(tmp);
+ /*
+ * Use the predefined upid nrs for levels ns->level down to
+ * ns->level - rel level
+ */
+ for (i = ns->level; rel_level >= 0; i--, rel_level--) {
+ nr = alloc_pidmap(tmp, pid_l, rel_level);
+ if (nr < 0)
  goto out free;
+ pid->numbers[i].nr = nr;
+ pid->numbers[i].ns = tmp;
+ tmp = tmp->parent;
+ }
+
+ if (pid_l) {
+ current->next_id->flag &= ~SYS_ID_PID;
+ pids free(pid I);
+ current->next_id->pid_ids = NULL;
+ }
+
+ * Let the lower levels upid nrs be automatically allocated
+ */
+ for (; i \ge 0; i--)
+ nr = alloc_pidmap(tmp, NULL, -1);
 if (nr < 0)
  goto out free;
```

```
@ @ -288,7 +348,7 @ @ out free:
 free_pidmap(pid->numbers + i);
 kmem_cache_free(ns->pid_cachep, pid);
pid = NULL;
+ pid = ERR PTR(nr):
 goto out;
Index: linux-2.6.25-rc3-mm1/kernel/fork.c
--- linux-2.6.25-rc3-mm1.orig/kernel/fork.c 2008-03-10 09:19:01.000000000 +0100
+++ linux-2.6.25-rc3-mm1/kernel/fork.c 2008-03-10 13:48:03.000000000 +0100
@ @ -1197,10 +1197,11 @ @ static struct task_struct *copy_process(
 goto bad_fork_cleanup_io;
 if (pid != &init_struct_pid) {
retval = -ENOMEM;
 pid = alloc_pid(task_active_pid_ns(p));
- if (!pid)
+ if (IS ERR(pid)) {
+ retval = PTR_ERR(pid);
  goto bad_fork_cleanup_io;
+ }
 if (clone_flags & CLONE_NEWPID) {
  retval = pid_ns_prepare_proc(task_active_pid_ns(p));
Containers mailing list
Containers@lists.linux-foundation.org
https://lists.linux-foundation.org/mailman/listinfo/containers
```

Subject: Re: [RFC][PATCH 4/4] PID: use the target ID specified in procfs Posted by Pavel Emelianov on Tue, 11 Mar 2008 12:04:39 GMT View Forum Message <> Reply to Message

```
Nadia.Derbey@bull.net wrote:

> @ @ -122,14 +122,26 @ @ static void free_pidmap(struct upid *upi

> atomic_inc(&map->nr_free);

> }

> -static int alloc_pidmap(struct pid_namespace *pid_ns)

> +static int alloc_pidmap(struct pid_namespace *pid_ns, struct pid_list *pid_l,

> + int level)
```

```
> {
 int i, offset, max_scan, pid, last = pid_ns->last_pid;
> struct pidmap *map;
> - pid = last + 1;
> - if (pid >= pid_max)
> - pid = RESERVED_PIDS;
> + if (!pid_l) {
> + pid = last + 1;
> + if (pid > = pid max)
> + pid = RESERVED_PIDS;
> + } else {
> + /*
> + * There's a target pid, so use it instead
> + BUG_ON(level < 0);
> + pid = PID_AT(pid_I, level);
> + if (pid >= pid_max)
> + return -EINVAL;
> + }
  offset = pid & BITS PER PAGE MASK;
  map = &pid_ns->pidmap[pid/BITS_PER_PAGE];
   max_scan = (pid_max + BITS_PER_PAGE - 1)/BITS_PER_PAGE - !offset;
> @ @ -153,9 +165,16 @ @ static int alloc_pidmap(struct pid_names
    do {
>
    if (!test_and_set_bit(offset, map->page)) {
>
     atomic_dec(&map->nr_free);
     pid ns->last pid = pid;
> -
      if (!pid_l)
      pid_ns->last_pid = pid;
      else
      pid_ns->last_pid = max(last,
        pid);
     return pid;
>
    }
> + if (pid_l)
    /* Target pid is already in use */
     return -EBUSY;
     offset = find_next_offset(map, offset);
     pid = mk pid(pid ns, map, offset);
>
> @ @ -179,7 +198,7 @ @ static int alloc_pidmap(struct pid_names)
>
   pid = mk_pid(pid_ns, map, offset);
>
>
> - return -1;
> + return -ENOMEM;
```

```
> }
> int next_pidmap(struct pid_namespace *pid_ns, int last)
As fas as this particular piece of code is concerned this all can
be shrunk down to
static int set_vpidmap(struct pid_namespace *ns, int pid)
    int offset:
    pidmap_t *map;
    offset = pid & BITS_PER_PAGE_MASK;
    map = ns->pidmap + vpid / BITS_PER_PAGE;
    if (unlikely(alloc_pidmap_page(map)))
         return -ENOMEM;
    if (test_and_set_bit(offset, map->page))
         return -EEXIST;
    atomic dec(&map->nr free);
    return pid;
}
where the alloc_pidmap_page is a consolidated part of code from alloc_pidmap.
And I'm scared of what the alloc_pid is going to become.
Containers mailing list
Containers@lists.linux-foundation.org
https://lists.linux-foundation.org/mailman/listinfo/containers
Subject: Re: [RFC][PATCH 4/4] PID: use the target ID specified in procfs
```

Posted by Nadia Derbey on Tue, 11 Mar 2008 15:28:45 GMT

```
Pavel Emelyanov wrote:
> Nadia.Derbey@bull.net wrote:
>>@@ -122,14 +122,26 @@ static void free pidmap(struct upid *upi
>> atomic_inc(&map->nr_free);
>> }
>>
>>-static int alloc_pidmap(struct pid_namespace *pid_ns)
>>+static int alloc_pidmap(struct pid_namespace *pid_ns, struct pid_list *pid_l,
>>+ int level)
```

```
>> {
>> int i, offset, max_scan, pid, last = pid_ns->last_pid;
>> struct pidmap *map;
>>
>>- pid = last + 1;
>>- if (pid >= pid_max)
>>- pid = RESERVED_PIDS;
>>+ if (!pid_l) {
>>+ pid = last + 1;
>>+ if (pid >= pid max)
>>+ pid = RESERVED_PIDS;
>>+ } else {
>>+ /*
>>+ * There's a target pid, so use it instead
>>+ */
>>+ BUG_ON(level < 0);
>>+ pid = PID AT(pid I, level);
>>+ if (pid >= pid_max)
>>+ return -EINVAL;
>>+ }
>>+
>> offset = pid & BITS PER PAGE MASK;
>> map = &pid_ns->pidmap[pid/BITS_PER_PAGE];
>> max_scan = (pid_max + BITS_PER_PAGE - 1)/BITS_PER_PAGE - !offset;
>>@@ -153,9 +165,16 @@ static int alloc_pidmap(struct pid_names
    do {
>>
     if (!test_and_set_bit(offset, map->page)) {
>>
      atomic_dec(&map->nr_free);
      pid ns->last pid = pid;
>>-
>>+
      if (!pid_l)
       pid_ns->last_pid = pid;
>>+
      else
>>+
       pid_ns->last_pid = max(last,
>>+
         pid);
>>+
      return pid;
>>
     }
>>
>>+ if (pid_l)
      /* Target pid is already in use */
>>+
      return -EBUSY;
     offset = find next offset(map, offset);
>>
     pid = mk pid(pid ns, map, offset);
>>
>>@@ -179,7 +198,7 @@ static int alloc_pidmap(struct pid_names
>>
>> pid = mk_pid(pid_ns, map, offset);
>> }
>>- return -1;
>>+ return -ENOMEM;
```

```
>> }
>>
>> int next_pidmap(struct pid_namespace *pid_ns, int last)
> As fas as this particular piece of code is concerned this all can
> be shrunk down to
> static int set_vpidmap(struct pid_namespace *ns, int pid)
> {
      int offset;
>
      pidmap_t *map;
>
>
      offset = pid & BITS_PER_PAGE_MASK;
>
      map = ns->pidmap + vpid / BITS_PER_PAGE;
>
>
      if (unlikely(alloc_pidmap_page(map)))
>
           return -ENOMEM;
>
>
      if (test_and_set_bit(offset, map->page))
>
           return -EEXIST;
>
>
      atomic_dec(&map->nr_free);
>
      return pid;
>
> }
>
> where the alloc_pidmap_page is a consolidated part of code from alloc_pidmap.
> And I'm scared of what the alloc pid is going to become.
>
It's true that I made alloc_pid() become uggly, but this patchest was
more intended to continue a discussion.
What we could do is the following (not compiled, not tested...):
struct pid *alloc_pid(struct pid_namespace *ns)
{
     struct pid *pid;
     enum pid type type;
     int i, nr;
     struct pid_namespace *tmp;
     struct upid *upid;
     pid = kmem_cache_alloc(ns->pid_cachep, GFP_KERNEL);
     if (!pid) {
          pid = ERR_PTR(-ENOMEM);
```

```
goto out;
     }
     tmp = ns;
     i = ns->level;
     if (current->next_id && (current->next_id->flag & SYS_ID_PID)) {
           tmp = set_predefined_pids(ns,
                    current->next_id->pid_ids);
           if (IS_ERR(tmp)) {
                nr = PTR\_ERR(tmp);
                goto out free;
           }
     }
      * Let the lower levels upid nrs be automatically allocated
     for (; i \ge 0; i--) {
           nr = alloc_pidmap(tmp, NULL, -1);
           if (nr < 0)
                goto out_free;
which would only add a test and a function call to alloc_pid() ==> more
readable.
with set_predefined_pids defined as follows (still not compiled, not
tested, ...):
struct pid_namespace *set_predefined_pids(struct pid_namespace *ns,
                          struct pid_list *pid_l)
{
     int rel_level;
     BUG_ON(!pid_l);
      rel_level = pid_l->npids - 1;
     if (rel_level > ns->level)
           return ERR_PTR(-EINVAL);
      * Use the predefined upid nrs for levels ns->level down to
      * ns->level - rel_level
      */
     for (; rel_level >= 0; i--, rel_level--) {
           nr = alloc_pidmap(tmp, pid_l, rel_level);
           if (nr < 0)
                return ERR_PTR(nr);
```

```
pid->numbers[i].nr = nr;
    pid->numbers[i].ns = tmp;
    tmp = tmp->parent;
}

current->next_id->flag &= ~SYS_ID_PID;
    pids_free(pid_I);
    current->next_id->pid_ids = NULL;

return tmp;
}

Don't you think that mixing this with your 1st proposal (the set_vpidmap() one), would make things look better?

Regards,
Nadia

Containers mailing list
Containers@lists.linux-foundation.org
```

https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: Re: [RFC][PATCH 4/4] PID: use the target ID specified in procfs Posted by Pavel Emelianov on Tue, 11 Mar 2008 15:37:37 GMT

```
Nadia Derbey wrote:
> Pavel Emelyanov wrote:
>> Nadia.Derbey@bull.net wrote:
>>
>>> @ @ -122,14 +122,26 @ @ static void free_pidmap(struct upid *upi
>>> atomic inc(&map->nr free);
>>> }
>>>
>>> -static int alloc_pidmap(struct pid_namespace *pid_ns)
>>> +static int alloc_pidmap(struct pid_namespace *pid_ns, struct pid_list *pid_l,
>>> + int level)
>>> {
>>> int i, offset, max scan, pid, last = pid ns->last pid;
>>> struct pidmap *map;
>>>
>>> - pid = last + 1;
>>> - if (pid >= pid_max)
>>> - pid = RESERVED_PIDS;
>>> + if (!pid_l) {
```

```
>>> + pid = last + 1;
>>> + if (pid >= pid max)
>>> + pid = RESERVED_PIDS;
>>> + } else {
>>> + /*
>>> + * There's a target pid, so use it instead
>>> + */
>>> + BUG_ON(level < 0);
>>> + pid = PID AT(pid I, level);
>>> + if (pid >= pid max)
>>> + return -EINVAL;
>>> + }
>>> +
>>> offset = pid & BITS_PER_PAGE_MASK;
>>> map = &pid_ns->pidmap[pid/BITS_PER_PAGE];
>>> max_scan = (pid_max + BITS_PER_PAGE - 1)/BITS_PER_PAGE - !offset;
>>> @ @ -153,9 +165,16 @ @ static int alloc_pidmap(struct pid_names
>>>
      do {
      if (!test_and_set_bit(offset, map->page)) {
>>>
       atomic_dec(&map->nr_free);
>>>
        pid_ns->last_pid = pid;
>>> -
       if (!pid I)
>>> +
         pid_ns->last_pid = pid;
>>> +
        else
>>> +
         pid_ns->last_pid = max(last,
>>> +
>>> +
           pid);
       return pid;
>>>
>>>
>>> + if (pid I)
>>> + /* Target pid is already in use */
       return -EBUSY:
>>> +
      offset = find_next_offset(map, offset);
>>>
      pid = mk_pid(pid_ns, map, offset);
>>>
>>> @ @ -179,7 +198,7 @ @ static int alloc_pidmap(struct pid_names
>>> pid = mk_pid(pid_ns, map, offset);
>>> }
>>> - return -1;
>>> + return -ENOMEM;
>>> }
>>> int next_pidmap(struct pid_namespace *pid_ns, int last)
>>
>> As fas as this particular piece of code is concerned this all can
>> be shrunk down to
>>
>> static int set vpidmap(struct pid namespace *ns, int pid)
```

```
>> {
        int offset:
>>
        pidmap_t *map;
>>
>>
        offset = pid & BITS_PER_PAGE_MASK;
>>
        map = ns->pidmap + vpid / BITS_PER_PAGE;
>>
>>
        if (unlikely(alloc_pidmap_page(map)))
>>
             return -ENOMEM;
>>
        if (test_and_set_bit(offset, map->page))
>>
             return -EEXIST;
>>
>>
        atomic_dec(&map->nr_free);
>>
        return pid;
>>
>> }
>> where the alloc_pidmap_page is a consolidated part of code from alloc_pidmap.
>> And I'm scared of what the alloc_pid is going to become.
>>
>>
> It's true that I made alloc_pid() become uggly, but this patchset was
> more intended to continue a discussion.
>
> What we could do is the following (not compiled, not tested...):
> struct pid *alloc pid(struct pid namespace *ns)
> {
       struct pid *pid;
>
       enum pid_type type;
>
       int i, nr;
>
       struct pid_namespace *tmp;
>
       struct upid *upid;
>
>
       pid = kmem_cache_alloc(ns->pid_cachep, GFP_KERNEL);
>
       if (!pid) {
>
            pid = ERR_PTR(-ENOMEM);
            goto out;
>
       }
>
>
       tmp = ns;
       i = ns - slevel;
>
       if (current->next_id && (current->next_id->flag & SYS_ID_PID)) {
>
            tmp = set predefined pids(ns,
>
                     current->next id->pid ids);
```

```
if (IS_ERR(tmp)) {
>
                  nr = PTR_ERR(tmp);
>
                  goto out_free;
>
            }
       }
>
>
>
        * Let the lower levels upid nrs be automatically allocated
>
>
       for (; i \ge 0; i--) {
>
             nr = alloc_pidmap(tmp, NULL, -1);
>
             if (nr < 0)
>
                  goto out_free;
>
> ....
> which would only add a test and a function call to alloc_pid() ==> more
> readable.
> with set_predefined_pids defined as follows (still not compiled, not
> tested, ...):
>
> struct pid_namespace *set_predefined_pids(struct pid_namespace *ns,
                            struct pid list *pid l)
> {
       int rel_level;
>
>
       BUG_ON(!pid_I);
>
>
       rel level = pid I->npids - 1;
>
       if (rel level > ns->level)
>
             return ERR_PTR(-EINVAL);
>
>
        * Use the predefined upid nrs for levels ns->level down to
>
        * ns->level - rel_level
>
        */
>
       for ( ; rel level >= 0; i--, rel level--) {
>
             nr = alloc_pidmap(tmp, pid_l, rel_level);
>
             if (nr < 0)
>
                  return ERR_PTR(nr);
>
>
             pid->numbers[i].nr = nr;
>
             pid->numbers[i].ns = tmp;
             tmp = tmp->parent;
>
       }
>
>
       current->next_id->flag &= ~SYS_ID_PID;
>
       pids free(pid I);
>
       current->next id->pid ids = NULL;
```

```
>
>
       return tmp;
> }
>
> Don't you think that mixing this with your 1st proposal (the
> set_vpidmap() one), would make things look better?
I'd prefer seeing
--- a/kernel/pid.c
+++ b/kernel/pid.c
@ @ -247,7 +247,7 @ @ struct pid *alloc_pid(struct pid_namespace *ns)
{
     struct pid *pid;
     enum pid_type type;
     int i, nr;
     int i, nr, req_nr;
     struct pid_namespace *tmp;
     struct upid *upid;
@@ -257,7 +257,11 @@ struct pid *alloc_pid(struct pid_namespace *ns)
     tmp = ns;
     for (i = ns->level; i >= 0; i--) {
          nr = alloc_pidmap(tmp);
           req_nr = get_required_pidnr(ns, i);
          if (req_nr > 0)
                nr = set pidmap(tmp, req nr);
           else
+
                nr = alloc_pidmap(tmp);
          if (nr < 0)
               goto out_free;
in alloc_pid() and not much than that.
> Regards,
> Nadia
Containers mailing list
Containers@lists.linux-foundation.org
https://lists.linux-foundation.org/mailman/listinfo/containers
```

Page 29 of 109 ---- Generated from OpenVZ Forum

## Subject: Re: [RFC][PATCH 4/4] PID: use the target ID specified in procfs Posted by Nadia Derbey on Tue, 11 Mar 2008 15:55:04 GMT

```
Pavel Emelyanov wrote:
> Nadia Derbey wrote:
>>Pavel Emelyanov wrote:
>>>Nadia.Derbey@bull.net wrote:
>>>
>>>
>>>@@ -122,14 +122,26 @@ static void free pidmap(struct upid *upi
>>>> atomic inc(&map->nr free);
>>>>}
>>>>
>>>-static int alloc_pidmap(struct pid_namespace *pid_ns)
>>>+static int alloc_pidmap(struct pid_namespace *pid_ns, struct pid_list *pid_l,
>>>+ int level)
>>>>{
>>>> int i, offset, max_scan, pid, last = pid_ns->last_pid;
>>> struct pidmap *map;
>>>>
>>> pid = last + 1;
>>>- if (pid >= pid max)
>>>- pid = RESERVED_PIDS;
>>>+ if (!pid_l) {
>>>+ pid = last + 1;
>>>+ if (pid >= pid_max)
>>>+ pid = RESERVED_PIDS;
>>>+ } else {
>>>+ /*
>>>+ * There's a target pid, so use it instead
>>>+ */
>>>+ BUG ON(level < 0);
>>>+ pid = PID AT(pid I, level);
>>>+ if (pid >= pid_max)
>>>+ return -EINVAL;
>>>+ }
>>>+
>>>> offset = pid & BITS_PER_PAGE_MASK;
>>>> map = &pid ns->pidmap[pid/BITS PER PAGE];
>>>> max_scan = (pid_max + BITS_PER_PAGE - 1)/BITS PER PAGE - !offset:
>>>@@ -153,9 +165,16 @@ static int alloc_pidmap(struct pid_names
>>>> do {
>>> if (!test_and_set_bit(offset, map->page)) {
      atomic_dec(&map->nr_free);
>>>>
        pid_ns->last_pid = pid;
>>>-
>>>+ if (!pid_l)
```

```
pid_ns->last_pid = pid;
>>>>+
         else
>>>+
         pid_ns->last_pid = max(last,
>>>>+
           pid);
>>>+
       return pid;
>>>>
>>>> }
>>>+ if (pid_l)
>>>+ /* Target pid is already in use */
>>>+ return -EBUSY;
>>> offset = find next offset(map, offset);
>>> pid = mk_pid(pid_ns, map, offset);
>>>> /*
>>>@@ -179,7 +198,7 @@ static int alloc_pidmap(struct pid_names
>>>> }
>>> pid = mk_pid(pid_ns, map, offset);
>>>> }
>>>- return -1;
>>>+ return -ENOMEM;
>>>>}
>>>>
>>>int next_pidmap(struct pid_namespace *pid_ns, int last)
>>>As fas as this particular piece of code is concerned this all can
>>>be shrunk down to
>>>
>>>static int set vpidmap(struct pid namespace *ns, int pid)
>>>{
        int offset:
>>>
        pidmap t *map;
>>>
>>>
        offset = pid & BITS PER PAGE MASK;
>>>
        map = ns->pidmap + vpid / BITS PER PAGE;
>>>
>>>
        if (unlikely(alloc_pidmap_page(map)))
>>>
             return -ENOMEM;
>>>
>>>
        if (test_and_set_bit(offset, map->page))
>>>
             return -EEXIST;
>>>
>>>
        atomic_dec(&map->nr_free);
>>>
        return pid;
>>>
>>>}
>>>
>>>where the alloc_pidmap_page is a consolidated part of code from alloc_pidmap.
>>>And I'm scared of what the alloc_pid is going to become.
>>>
>>>
```

```
>>
>>It's true that I made alloc_pid() become uggly, but this patchset was
>>more intended to continue a discussion.
>>
>>What we could do is the following (not compiled, not tested...):
>>
>>struct pid *alloc_pid(struct pid_namespace *ns)
>>{
        struct pid *pid;
>>
        enum pid type type;
>>
        int i, nr;
>>
        struct pid namespace *tmp;
>>
        struct upid *upid;
>>
>>
        pid = kmem_cache_alloc(ns->pid_cachep, GFP_KERNEL);
>>
>>
        if (!pid) {
             pid = ERR_PTR(-ENOMEM);
>>
             goto out;
>>
        }
>>
>>
>>
        tmp = ns;
        i = ns->level;
>>
>>
        if (current->next_id && (current->next_id->flag & SYS_ID_PID)) {
>>
             tmp = set_predefined_pids(ns,
>>
                      current->next_id->pid_ids);
>>
             if (IS_ERR(tmp)) {
>>
                  nr = PTR ERR(tmp);
                  goto out free;
>>
             }
>>
        }
>>
>>
>>
         * Let the lower levels upid nrs be automatically allocated
>>
         */
>>
        for ( : i >= 0 : i--) 
>>
             nr = alloc_pidmap(tmp, NULL, -1);
>>
             if (nr < 0)
>>
                  goto out_free;
>>
>>....
>>
>>which would only add a test and a function call to alloc_pid() ==> more
>>readable.
>>with set_predefined_pids defined as follows (still not compiled, not
>>tested, ...):
>>
>>struct pid_namespace *set_predefined_pids(struct pid_namespace *ns,
                            struct pid_list *pid_l)
>>
```

```
>>{
        int rel level;
>>
>>
        BUG_ON(!pid_I);
>>
>>
        rel_level = pid_l->npids - 1;
>>
        if (rel level > ns->level)
>>
             return ERR_PTR(-EINVAL);
>>
>>
>>
         * Use the predefined upid nrs for levels ns->level down to
>>
         * ns->level - rel level
>>
         */
>>
        for (; rel_level >= 0; i--, rel_level--) {
>>
             nr = alloc_pidmap(tmp, pid_l, rel_level);
>>
             if (nr < 0)
>>
                   return ERR_PTR(nr);
>>
>>
             pid->numbers[i].nr = nr;
>>
             pid->numbers[i].ns = tmp;
>>
             tmp = tmp->parent;
>>
        }
>>
>>
        current->next_id->flag &= ~SYS_ID_PID;
>>
        pids_free(pid_l);
>>
        current->next_id->pid_ids = NULL;
>>
>>
        return tmp;
>>
>>}
>>
>>
>>Don't you think that mixing this with your 1st proposal (the
>>set_vpidmap() one), would make things look better?
>
> I'd prefer seeing
> --- a/kernel/pid.c
> +++ b/kernel/pid.c
> @ @ -247,7 +247,7 @ @ struct pid *alloc_pid(struct pid_namespace *ns)
> {
       struct pid *pid;
>
       enum pid_type type;
>
> -
       int i, nr;
       int i, nr, req_nr;
> +
       struct pid_namespace *tmp;
>
       struct upid *upid;
>
```

```
> @ @ -257,7 +257,11 @ @ struct pid *alloc_pid(struct pid_namespace *ns)
>
       tmp = ns;
>
       for (i = ns - | evel; i > = 0; i - -) {
            nr = alloc_pidmap(tmp);
             req_nr = get_required_pidnr(ns, i);
             if (req_nr > 0)
                  nr = set_pidmap(tmp, req_nr);
             else
                  nr = alloc pidmap(tmp);
            if (nr < 0)
                 goto out free;
>
>
> in alloc_pid() and not much than that.
>
But doing this in the existing path, we are unconditionally adding for
each level:
. a call to get required pidnr()
. a test (on reg nr value)
while with what I proposed in my previous mail I'm adding only 1 test to
the existing alloc_pid() path. But I agree with that it may be still not
perfect.
Or may be I missed something?
Regards,
Nadia
Containers mailing list
Containers@lists.linux-foundation.org
https://lists.linux-foundation.org/mailman/listinfo/containers
```

Subject: Re: [RFC][PATCH 4/4] PID: use the target ID specified in procfs Posted by serue on Tue, 11 Mar 2008 16:47:25 GMT

```
Quoting Pavel Emelyanov (xemul@openvz.org):

> Nadia Derbey wrote:

> Pavel Emelyanov wrote:

> Nadia.Derbey@bull.net wrote:

> >>

> >> @ @ -122,14 +122,26 @ @ static void free_pidmap(struct upid *upi

> >> atomic_inc(&map->nr_free);
```

```
>>>> }
>>>>
>>> -static int alloc_pidmap(struct pid_namespace *pid_ns)
>>>> +static int alloc_pidmap(struct pid_namespace *pid_ns, struct pid_list *pid_l,
>>> + int level)
>>>> {
>>>> int i, offset, max_scan, pid, last = pid_ns->last_pid;
>>> struct pidmap *map;
> >>>
> >> - pid = last + 1;
> >>> - if (pid >= pid_max)
>>>> - pid = RESERVED PIDS;
>>>> + if (!pid_l) {
>>>+ pid = last + 1;
>>> + if (pid >= pid_max)
>>>> + pid = RESERVED_PIDS;
>>>> + } else {
>>>+ /*
>>> + * There's a target pid, so use it instead
>>>+ */
>>> + BUG_ON(level < 0);
>>> + pid = PID AT(pid I, level);
>>>> + if (pid >= pid_max)
>>> + return -EINVAL;
> >>> + }
>>>> +
>>>> offset = pid & BITS_PER_PAGE_MASK;
>>>> map = &pid ns->pidmap[pid/BITS PER PAGE];
>>>> max scan = (pid max + BITS PER PAGE - 1)/BITS PER PAGE - !offset;
>>>> @ @ -153,9 +165,16 @ @ static int alloc_pidmap(struct pid_names
      do {
>>>>
        if (!test_and_set_bit(offset, map->page)) {
> >>>
         atomic_dec(&map->nr_free);
> >>>
         pid_ns->last_pid = pid;
> >>> -
          if (!pid_l)
> >>> +
         pid_ns->last_pid = pid;
> >>> +
          else
>>>> +
          pid_ns->last_pid = max(last,
> >>> +
> >>> +
            pid);
         return pid;
> >>>
        }
> >>>
>>> + if (pid_l)
         /* Target pid is already in use */
> >>> +
          return -EBUSY;
> >>> +
        offset = find_next_offset(map, offset);
> >>>
        pid = mk_pid(pid_ns, map, offset);
> >>>
      /*
> >>>
>>>> @ @ -179,7 +198,7 @ @ static int alloc_pidmap(struct pid_names
```

```
>>>> }
>>> pid = mk_pid(pid_ns, map, offset);
>>>> }
>>> - return -1;
>>> + return -ENOMEM;
> >>> }
> >>>
>>>> int next_pidmap(struct pid_namespace *pid_ns, int last)
>>> As fas as this particular piece of code is concerned this all can
>>> be shrunk down to
> >>
>>> static int set_vpidmap(struct pid_namespace *ns, int pid)
> >> {
         int offset;
> >>
         pidmap_t *map;
> >>
> >>
          offset = pid & BITS_PER_PAGE_MASK;
> >>
         map = ns->pidmap + vpid / BITS_PER_PAGE;
> >>
> >>
         if (unlikely(alloc_pidmap_page(map)))
> >>
               return -ENOMEM;
> >>
> >>
         if (test_and_set_bit(offset, map->page))
> >>
               return -EEXIST;
> >>
> >>
          atomic_dec(&map->nr_free);
> >>
          return pid;
> >>
> >> }
> >>
>>> where the alloc pidmap page is a consolidated part of code from alloc pidmap.
> >>
> >> And I'm scared of what the alloc_pid is going to become.
> >>
>> It's true that I made alloc_pid() become uggly, but this patchset was
> > more intended to continue a discussion.
>> What we could do is the following (not compiled, not tested...):
> >
> > struct pid *alloc_pid(struct pid_namespace *ns)
> > {
         struct pid *pid;
> >
         enum pid_type type;
> >
         int i, nr;
> >
         struct pid namespace *tmp;
> >
         struct upid *upid;
> >
```

```
> >
> >
          pid = kmem_cache_alloc(ns->pid_cachep, GFP_KERNEL);
         if (!pid) {
> >
              pid = ERR_PTR(-ENOMEM);
               goto out;
> >
         }
> >
> >
         tmp = ns;
> >
         i = ns->level;
> >
> >
> >
         if (current->next_id && (current->next_id->flag & SYS_ID_PID)) {
               tmp = set predefined pids(ns,
> >
                        current->next_id->pid_ids);
> >
              if (IS_ERR(tmp)) {
> >
                    nr = PTR\_ERR(tmp);
> >
                    goto out_free;
> >
              }
> >
         }
> >
> >
> >
          * Let the lower levels upid nrs be automatically allocated
> >
> >
         for (; i \ge 0; i--) {
> >
              nr = alloc_pidmap(tmp, NULL, -1);
> >
              if (nr < 0)
> >
                    goto out_free;
> >
>> ....
>> which would only add a test and a function call to alloc pid() ==> more
> > readable.
>> with set predefined pids defined as follows (still not compiled, not
> > tested, ...):
> >
>> struct pid_namespace *set_predefined_pids(struct pid_namespace *ns,
                              struct pid_list *pid_l)
> >
> > {
         int rel_level;
> >
> >
         BUG_ON(!pid_I);
> >
         rel level = pid I->npids - 1;
> >
         if (rel_level > ns->level)
               return ERR_PTR(-EINVAL);
> >
> >
> >
          * Use the predefined upid nrs for levels ns->level down to
> >
          * ns->level - rel level
> >
          */
> >
```

```
for (; rel_level >= 0; i--, rel_level--) {
> >
              nr = alloc_pidmap(tmp, pid_l, rel_level);
> >
              if (nr < 0)
> >
                    return ERR_PTR(nr);
> >
              pid->numbers[i].nr = nr;
> >
              pid->numbers[i].ns = tmp;
> >
              tmp = tmp->parent;
> >
         }
> >
> >
> >
         current->next_id->flag &= ~SYS_ID_PID;
         pids free(pid I);
> >
         current->next_id->pid_ids = NULL;
> >
> >
         return tmp;
> >
>>}
> >
>> Don't you think that mixing this with your 1st proposal (the
> > set_vpidmap() one), would make things look better?
> I'd prefer seeing
> --- a/kernel/pid.c
> +++ b/kernel/pid.c
> @ @ -247,7 +247,7 @ @ struct pid *alloc_pid(struct pid_namespace *ns)
>
       struct pid *pid;
>
       enum pid type type;
>
       int i, nr;
       int i, nr, req_nr;
       struct pid_namespace *tmp;
>
       struct upid *upid;
>
> @ @ -257,7 +257,11 @ @ struct pid *alloc_pid(struct pid_namespace *ns)
>
       tmp = ns;
>
       for (i = ns->level; i >= 0; i--) {
>
            nr = alloc_pidmap(tmp);
            req_nr = get_required_pidnr(ns, i);
> +
            if (req nr > 0)
                  nr = set_pidmap(tmp, req_nr);
I assume you mean set_vpidmap(tmp, req_nr); here?
            else
                  nr = alloc_pidmap(tmp);
            if (nr < 0)
>
```

```
goto out_free;
>
>
> in alloc_pid() and not much than that.
So get_required_pidnr(ns, i) would do something like
int get_required_pidnr(struct pid_namespace *ns, int i)
if (current->next id && (current->next id->flag & SYS ID PID)) {
 pid_I = current->next_id->pid_ids;
 if (!pid I) return 0;
 rel_level = pid_l->npids - 1;
 if (rel_level <= i)
 return PID_AT(pid_I, i);
}
return 0;
?
> > Regards,
> > Nadia
> >
>
> Containers mailing list
> Containers@lists.linux-foundation.org
> https://lists.linux-foundation.org/mailman/listinfo/containers
Containers mailing list
Containers@lists.linux-foundation.org
```

https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: Re: [RFC][PATCH 4/4] PID: use the target ID specified in procfs Posted by Pavel Emelianov on Tue, 11 Mar 2008 16:55:44 GMT View Forum Message <> Reply to Message

```
Serge E. Hallyn wrote:

> Quoting Pavel Emelyanov (xemul@openvz.org):

>> Nadia Derbey wrote:

>>> Pavel Emelyanov wrote:

>>> Nadia.Derbey@bull.net wrote:

>>>>

>>>> @ @ -122,14 +122,26 @ @ static void free_pidmap(struct upid *upi >>>> atomic_inc(&map->nr_free);
```

```
>>>> }
>>>>
>>>> -static int alloc_pidmap(struct pid_namespace *pid_ns)
>>>> +static int alloc_pidmap(struct pid_namespace *pid_ns, struct pid_list *pid_l,
>>>> + int level)
>>>> {
>>>> int i, offset, max_scan, pid, last = pid_ns->last_pid;
>>>> struct pidmap *map;
>>>>
>>>> - pid = last + 1;
>>>> - if (pid >= pid_max)
>>>> - pid = RESERVED_PIDS;
>>>> + if (!pid_l) {
>>>> + pid = last + 1;
>>>> + if (pid >= pid_max)
>>>> + pid = RESERVED_PIDS;
>>>> + } else {
>>>> + /*
>>>> + * There's a target pid, so use it instead
>>>> + */
>>>> + BUG_ON(level < 0);
>>>> + pid = PID AT(pid I, level);
>>>> + if (pid >= pid_max)
>>>> + return -EINVAL;
>>>> + }
>>>> +
>>>> offset = pid & BITS_PER_PAGE_MASK;
>>>> map = &pid ns->pidmap[pid/BITS PER PAGE];
>>>> max_scan = (pid_max + BITS_PER_PAGE - 1)/BITS_PER PAGE - !offset:
>>>> @ @ -153,9 +165,16 @ @ static int alloc_pidmap(struct pid_names
>>>> do {
        if (!test_and_set_bit(offset, map->page)) {
>>>>
         atomic_dec(&map->nr_free);
>>>>
          pid_ns->last_pid = pid;
>>>> -
         if (!pid_l)
>>>> +
         pid_ns->last_pid = pid;
>>>> +
          else
>>>> +
           pid ns->last pid = max(last,
>>>> +
>>>> +
             pid);
         return pid;
>>>>
        }
>>>>
>>>> + if (pid_l)
         /* Target pid is already in use */
>>>> +
          return -EBUSY;
>>>> +
        offset = find_next_offset(map, offset);
>>>>
        pid = mk_pid(pid_ns, map, offset);
>>>>
>>>>
>>>> @ @ -179,7 +198,7 @ @ static int alloc pidmap(struct pid names
```

```
>>>>> }
>>>> pid = mk_pid(pid_ns, map, offset);
>>>> }
>>>> - return -1;
>>>> + return -ENOMEM;
>>>> }
>>>>
>>>> int next_pidmap(struct pid_namespace *pid_ns, int last)
>>>> As fas as this particular piece of code is concerned this all can
>>>> be shrunk down to
>>>>
>>> static int set vpidmap(struct pid namespace *ns, int pid)
>>>> {
          int offset:
>>>>
          pidmap_t *map;
>>>>
>>>>
          offset = pid & BITS PER PAGE MASK;
>>>>
          map = ns->pidmap + vpid / BITS PER PAGE;
>>>>
>>>>
          if (unlikely(alloc_pidmap_page(map)))
>>>>
               return -ENOMEM;
>>>>
>>>>
          if (test_and_set_bit(offset, map->page))
>>>>
               return -EEXIST:
>>>>
>>>>
          atomic_dec(&map->nr_free);
>>>>
          return pid;
>>>>
>>>> }
>>>>
>>>> where the alloc_pidmap_page is a consolidated part of code from alloc_pidmap.
>>>> And I'm scared of what the alloc_pid is going to become.
>>>>
>>>>
>>> It's true that I made alloc_pid() become uggly, but this patchset was
>>> more intended to continue a discussion.
>>>
>>> What we could do is the following (not compiled, not tested...):
>>> struct pid *alloc pid(struct pid namespace *ns)
>>> {
         struct pid *pid;
>>>
>>>
         enum pid_type type;
         int i, nr;
>>>
         struct pid_namespace *tmp;
>>>
         struct upid *upid;
>>>
>>>
         pid = kmem cache alloc(ns->pid cachep, GFP KERNEL);
>>>
```

```
if (!pid) {
>>>
               pid = ERR_PTR(-ENOMEM);
>>>
               goto out;
>>>
          }
>>>
>>>
          tmp = ns;
>>>
          i = ns->level;
>>>
>>>
          if (current->next id && (current->next id->flag & SYS ID PID)) {
>>>
               tmp = set predefined pids(ns,
>>>
>>>
                        current->next_id->pid_ids);
               if (IS ERR(tmp)) {
>>>
                    nr = PTR\_ERR(tmp);
>>>
                    goto out_free;
>>>
               }
>>>
>>>
          }
>>>
>>>
           * Let the lower levels upid nrs be automatically allocated
>>>
           */
>>>
          for (; i \ge 0; i--) {
>>>
               nr = alloc pidmap(tmp, NULL, -1);
>>>
               if (nr < 0)
>>>
                    goto out_free;
>>>
>>> ....
>>>
>>> which would only add a test and a function call to alloc_pid() ==> more
>>> readable.
>>> with set predefined pids defined as follows (still not compiled, not
>>> tested, ...):
>>>
>>> struct pid_namespace *set_predefined_pids(struct pid_namespace *ns,
                              struct pid_list *pid_l)
>>>
>>> {
          int rel_level;
>>>
>>>
          BUG_ON(!pid_I);
>>>
>>>
          rel level = pid l->npids - 1;
>>>
          if (rel level > ns->level)
>>>
               return ERR PTR(-EINVAL);
>>>
>>>
>>>
           * Use the predefined upid nrs for levels ns->level down to
>>>
           * ns->level - rel level
>>>
>>>
          for (; rel level >= 0; i--, rel level--) {
>>>
               nr = alloc pidmap(tmp, pid I, rel level);
>>>
```

```
if (nr < 0)
>>>
>>>
                    return ERR_PTR(nr);
>>>
               pid->numbers[i].nr = nr;
>>>
               pid->numbers[i].ns = tmp;
>>>
               tmp = tmp->parent;
>>>
          }
>>>
>>>
          current->next_id->flag &= ~SYS_ID_PID;
>>>
          pids free(pid I);
>>>
>>>
          current->next_id->pid_ids = NULL;
>>>
          return tmp;
>>>
>>> }
>>>
>>>
>>> Don't you think that mixing this with your 1st proposal (the
>>> set_vpidmap() one), would make things look better?
>> I'd prefer seeing
>>
>> --- a/kernel/pid.c
>> +++ b/kernel/pid.c
>> @ @ -247,7 +247,7 @ @ struct pid *alloc_pid(struct pid_namespace *ns)
>> {
>>
        struct pid *pid;
        enum pid_type type;
>>
        int i, nr;
>> -
        int i, nr, req_nr;
>> +
        struct pid namespace *tmp;
>>
        struct upid *upid;
>>
>> @ @ -257,7 +257,11 @ @ struct pid *alloc_pid(struct pid_namespace *ns)
>>
>>
        tmp = ns;
        for (i = ns - | evel; i > = 0; i - -) 
>>
             nr = alloc pidmap(tmp);
>> -
              req_nr = get_required_pidnr(ns, i);
>> +
>> +
              if (req_nr > 0)
                   nr = set_pidmap(tmp, req_nr);
>> +
> I assume you mean set vpidmap(tmp, req nr); here?
:) or however this one is called.
              else
>> +
                   nr = alloc_pidmap(tmp);
>> +
             if (nr < 0)
>>
                  goto out free;
>>
```

```
>>
>>
>> in alloc_pid() and not much than that.
> So get_required_pidnr(ns, i) would do something like
> int get_required_pidnr(struct pid_namespace *ns, int i)
> {
> if (current->next id && (current->next id->flag & SYS ID PID)) {
> pid I = current->next id->pid ids;
> if (!pid_l) return 0;
> rel level = pid l->npids - 1;
> if (rel_level <= i)</pre>
  return PID_AT(pid_I, i);
> }
> return 0;
> }
>?
Well, yes, sort of. I haven't looked close to this part of patch,
but looks correct.
>>> Regards.
>>> Nadia
>>>
>>
>> Containers mailing list
>> Containers@lists.linux-foundation.org
>> https://lists.linux-foundation.org/mailman/listinfo/containers
Containers mailing list
Containers@lists.linux-foundation.org
https://lists.linux-foundation.org/mailman/listinfo/containers
```

Subject: Re: [RFC][PATCH 4/4] PID: use the target ID specified in procfs Posted by serue on Tue, 11 Mar 2008 17:53:28 GMT

View Forum Message <> Reply to Message

Quoting Pavel Emelyanov (xemul@openvz.org):
> Serge E. Hallyn wrote:
> > Quoting Pavel Emelyanov (xemul@openvz.org):
> >> Nadia Derbey wrote:
> >>> Pavel Emelyanov wrote:
> >>> Nadia.Derbey@bull.net wrote:

```
>>>>
>>>>> @ @ -122,14 +122,26 @ @ static void free_pidmap(struct upid *upi
>>>>> atomic_inc(&map->nr_free);
>>>>> }
>>>>>
>>>> -static int alloc_pidmap(struct pid_namespace *pid_ns)
>>>>> +static int alloc_pidmap(struct pid_namespace *pid_ns, struct pid_list *pid_l,
>>>>> + int level)
>>>>> {
>>>>> int i, offset, max scan, pid, last = pid ns->last pid;
>>>>> struct pidmap *map;
>>>>>
>>>>> - pid = last + 1;
>>>>> - if (pid >= pid_max)
>>>>> - pid = RESERVED_PIDS;
>>>>> + if (!pid_l) {
>>>>>+ pid = last + 1;
>>>>> + if (pid >= pid_max)
>>>>> + pid = RESERVED_PIDS;
>>>>> + } else {
>>>>> + /*
>>>>> + * There's a target pid, so use it instead
>>>>> + */
>>>> + BUG_ON(level < 0);
>>>> + pid = PID_AT(pid_I, level);
>>>>> + if (pid >= pid_max)
>>>>> + return -EINVAL;
> >>>> + }
>>>>> +
>>>>> offset = pid & BITS_PER_PAGE_MASK;
>>>>> map = &pid ns->pidmap[pid/BITS PER PAGE];
>>>>> max_scan = (pid_max + BITS_PER_PAGE - 1)/BITS_PER_PAGE - !offset;
>>>>> @ @ -153,9 +165,16 @ @ static int alloc_pidmap(struct pid_names
>>>>> do {
          if (!test_and_set_bit(offset, map->page)) {
>>>>>
          atomic dec(&map->nr free);
>>>>>
           pid_ns->last_pid = pid;
> >>>> -
          if (!pid I)
> >>>> +
           pid_ns->last_pid = pid;
>>>>> +
> >>>> +
            else
            pid ns->last pid = max(last,
> >>>> +
              pid);
>>>>> +
          return pid;
>>>>>
          }
>>>>>
>>>> + if (pid_l)
>>>>> + /* Target pid is already in use */
>>>>> + return -EBUSY;
>>>>> offset = find next offset(map, offset);
```

```
pid = mk_pid(pid_ns, map, offset);
>>>>>
>>>>>
>>>>> @ @ -179,7 +198,7 @ @ static int alloc_pidmap(struct pid_names
>>>>> }
>>>> pid = mk_pid(pid_ns, map, offset);
>>>>> }
>>>>> - return -1;
>>>> + return -ENOMEM;
>>>>> }
>>>>>
>>>>> int next_pidmap(struct pid_namespace *pid_ns, int last)
>>>> As fas as this particular piece of code is concerned this all can
>>>> be shrunk down to
> >>>
>>>> static int set_vpidmap(struct pid_namespace *ns, int pid)
>>>> {
           int offset:
>>>>
           pidmap_t *map;
>>>>
>>>>
           offset = pid & BITS_PER_PAGE_MASK;
>>>>
           map = ns->pidmap + vpid / BITS_PER_PAGE;
>>>>
> >>>
           if (unlikely(alloc_pidmap_page(map)))
>>>>
                return -ENOMEM:
>>>>
>>>>
           if (test_and_set_bit(offset, map->page))
>>>>
                return -EEXIST;
>>>>
>>>>
           atomic_dec(&map->nr_free);
>>>>
           return pid;
>>>>
>>>>> }
> >>>
>>>> where the alloc_pidmap_page is a consolidated part of code from alloc_pidmap.
>>>> And I'm scared of what the alloc_pid is going to become.
>>>>
>>>>
>>>> It's true that I made alloc pid() become uggly, but this patchset was
>>> more intended to continue a discussion.
> >>>
>>>> What we could do is the following (not compiled, not tested...):
>>> struct pid *alloc_pid(struct pid_namespace *ns)
> >>> {
           struct pid *pid;
> >>>
           enum pid_type type;
> >>>
           int i, nr;
> >>>
> >>>
           struct pid namespace *tmp;
```

```
struct upid *upid;
> >>>
> >>>
            pid = kmem_cache_alloc(ns->pid_cachep, GFP_KERNEL);
> >>>
            if (!pid) {
> >>>
                 pid = ERR_PTR(-ENOMEM);
> >>>
                 goto out;
> >>>
            }
> >>>
> >>>
            tmp = ns;
> >>>
            i = ns->level;
> >>>
> >>>
            if (current->next id && (current->next id->flag & SYS ID PID)) {
> >>>
                 tmp = set_predefined_pids(ns,
> >>>
                          current->next_id->pid_ids);
> >>>
                 if (IS_ERR(tmp)) {
> >>>
                      nr = PTR\_ERR(tmp);
> >>>
                      goto out free:
> >>>
                 }
> >>>
            }
> >>>
> >>>
> >>>
            * Let the lower levels upid nrs be automatically allocated
> >>>
            */
> >>>
            for (; i \ge 0; i--)
> >>>
                 nr = alloc_pidmap(tmp, NULL, -1);
> >>>
                 if (nr < 0)
> >>>
                      goto out_free;
> >>>
>>>> ....
> >>>
>>>> which would only add a test and a function call to alloc_pid() ==> more
>>>> readable.
>>>> with set_predefined_pids defined as follows (still not compiled, not
> >>> tested, ...):
> >>>
>>>> struct pid_namespace *set_predefined_pids(struct pid_namespace *ns,
                                struct pid_list *pid_l)
> >>>
> >>> {
            int rel level;
> >>>
> >>>
            BUG_ON(!pid_l);
> >>>
> >>>
            rel level = pid l->npids - 1;
> >>>
            if (rel_level > ns->level)
> >>>
                 return ERR_PTR(-EINVAL);
> >>>
> >>>
> >>>
            * Use the predefined upid nrs for levels ns->level down to
> >>>
            * ns->level - rel level
> >>>
```

```
*/
> >>>
            for ( ; rel_level >= 0; i--, rel_level--) {
> >>>
                 nr = alloc_pidmap(tmp, pid_l, rel_level);
> >>>
                 if (nr < 0)
> >>>
                      return ERR_PTR(nr);
> >>>
> >>>
                 pid->numbers[i].nr = nr:
> >>>
                 pid->numbers[i].ns = tmp;
> >>>
                 tmp = tmp->parent;
> >>>
            }
> >>>
> >>>
            current->next_id->flag &= ~SYS_ID_PID;
> >>>
            pids_free(pid_l);
> >>>
            current->next_id->pid_ids = NULL;
> >>>
> >>>
>>>>
            return tmp;
> >>> }
> >>>
>>>>
>>>> Don't you think that mixing this with your 1st proposal (the
>>>> set_vpidmap() one), would make things look better?
>>> I'd prefer seeing
> >>
>>> --- a/kernel/pid.c
> >> +++ b/kernel/pid.c
>>> @ @ -247,7 +247,7 @ @ struct pid *alloc_pid(struct pid_namespace *ns)
>>> {
          struct pid *pid;
> >>
          enum pid type type;
> >>
> >> -
          int i, nr;
          int i, nr, req_nr;
> >> +
          struct pid_namespace *tmp;
> >>
          struct upid *upid;
> >>
> >>
>>> @@ -257,7 +257,11 @@ struct pid *alloc_pid(struct pid_namespace *ns)
> >>
          tmp = ns;
> >>
          for (i = ns->level; i >= 0; i--) {
> >>
               nr = alloc_pidmap(tmp);
               req_nr = get_required_pidnr(ns, i);
> >> +
               if (req nr > 0)
> >> +
                     nr = set_pidmap(tmp, req_nr);
> >> +
> >
> > I assume you mean set_vpidmap(tmp, req_nr); here?
> :) or however this one is called.
```

Right, I just meant did you mean the same fn as in your previous

msg:) Don't care what it's called, actual set\_pidmap probably is better, as 'virtual' isn't quite right.

```
else
> >> +
                     nr = alloc_pidmap(tmp);
> >> +
               if (nr < 0)
                    goto out_free;
> >>
> >>
> >>
>>> in alloc pid() and not much than that.
>> So get required pidnr(ns, i) would do something like
> > int get_required_pidnr(struct pid_namespace *ns, int i)
> > {
>> if (current->next_id && (current->next_id->flag & SYS_ID_PID)) {
>> pid I = current->next id->pid ids:
>> if (!pid_l) return 0;
>> rel level = pid I->npids - 1;
>> if (rel_level <= i)
>> return PID AT(pid I, i);
>> }
> > return 0;
> > }
> >
>>?
> Well, yes, sort of. I haven't looked close to this part of patch,
> but looks correct.
```

Right the alloc\_pidmap() changes will probably be pretty much the same no matter how we do set\_it(), so it's worth discussing. But I'm particularly curious to see what opinions are on the sys\_setid().

-serge

Containers mailing list

Containers mailing list
Containers@lists.linux-foundation.org
https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: Re: [RFC][PATCH 4/4] PID: use the target ID specified in procfs Posted by ebiederm on Wed, 12 Mar 2008 19:58:56 GMT View Forum Message <> Reply to Message

"Nadia Derbey" <Nadia.Derbey@bull.net> writes:

- > A couple of weeks ago, a discussion has started after Pierre's proposal for
- > a new syscall to change an ipc id (see thread

```
> http://lkml.org/lkml/2008/1/29/209).
>
> Oren's suggestion was to force an object's id during its creation, rather
> than 1. create it, 2. change its id.
> So here is an implementation of what Oren has suggested.
> 2 new files are defined under /proc/self:
  . next ipcid --> next id to use for ipc object creation
  . next_pids --> next upid nr(s) to use for next task to be forked
             (see patch #2 for more details).
>
> When one of these files (or both of them) is filled, a structure pointed to
> by the calling task struct is filled with these ids.
>
> Then, when the object is created, the id(s) present in that structure are
> used, instead of the default ones.
> A couple of weeks ago, a discussion has started after Pierre's proposal for
> a new syscall to change an ipc id (see thread
> http://lkml.org/lkml/2008/1/29/209).
>
> Oren's suggestion was to force an object's id during its creation, rather
> than 1. create it, 2. change its id.
>
> So here is an implementation of what Oren has suggested.
> 2 new files are defined under /proc/self:
  . next_ipcid --> next id to use for ipc object creation
  . next pids --> next upid nr(s) to use for next task to be forked
             (see patch #2 for more details).
>
> When one of these files (or both of them) is filled, a structure pointed to
> by the calling task struct is filled with these ids.
> Then, when the object is created, the id(s) present in that structure are
> used, instead of the default ones.
"Serge E. Hallyn" <serue@us.ibm.com> writes:
> Right the alloc_pidmap() changes will probably be pretty much the same
```

- > no matter how we do set\_it(), so it's worth discussing. But I'm
- > particularly curious to see what opinions are on the sys\_setid().

A couple of comments. With respect to alloc\_pidmap we already have the necessary controls (a minimum and a maximum) in place for the allocation. So except for double checking that those controls are exported

in /proc/sys we don't necessarily need to do anything, special.

Just play games with the minimum pid value before you fork.

Second at least to get the memory map correct we need additional kernel support.

Third to actually get the values out it appears we need additional kernel support as well. From my limited playing with these things at least parts of the code were easier to implement in the kernel. The hoops you have to go to restore a single process (without threads) are absolutely horrendous in user space.

So this patchset whether it is setid or setting the id at creation time seems to be jumping the gun. For some namespaces renames are valid and we can support them. For other namespaces setting the id is a big no-no, and possibly even controlling the id at creation time is a problem (at least in the general sense). Because if you can easily control the id you may be able to more easily exploit security holes.

I'm not at all inclined to make it easy for userspace to rename or set the id of a new resource unless it already makes sense in that namespace.

We need to limit anything in a checkpoint to user space visible state. For sockets this can get fairly abstract since on the wire state of a tcp socket is in some sense user visible. However it should not include things that user space can never see like socket hash values.

Partly what this set of patches demonstrates is that it is fairly straight forward to restore ids. Getting the little details of the proper maintainable user space interface correct is harder.

The goal with any userspace implementation is to that we can separate policy form mechanism. So what are the trade offs for various approaches.

At least for inspection at the checkpoint side it would be nice for debugging applications to easily get at all of the user space visible state. So there is an argument for making state that is only indirectly visible, visible for diagnostic and debugging purposes.

For saving the state to disk it appears we need to stop all of the

processes in our container. Again something a debugging application of an entire container may want to do. Although we also want to stop the hardware queues for things like networking so we don't transmit or possibly receive new packets either.

We want a checkpoint/restart to be essentially atomic, with non of the tasks that we stop being able to prove that they ran while the checkpoint was being taken. Mostly this is an interprocess communication blackout, but there may be more to it then that.

We want checkpoint/restart if possible to be incremental. So we can perform actions like live migration efficiently if most of the data is not changing.

So there is an argument to perform the work piecemeal instead of in one big shot. Although if we can load data from wherever into the kernel data structures quickly it may not be a big deal.

We also want the transfer of state to be fast. Which tends to argue in the other direction. That we want a bulk operation that can save out everything and restore everything quickly.

We also want a design that we can implement incrementally. So that we can avoid supporting everything at first and if there is state that we should save that we can't (or similarly state that we should restore but we can't) the save/restore fails. Until that part is implemented.

Further we need to finish difficult things like sysfs support and proc support for simply running applications in containers.

So while I think it is good to be thinking and playing with these ideas now. I think having a more complete story and not pecking on the pieces right now is important.

My inclination is that create with a specified set of ids is the proper internal kernel API, so we don't have rework things later, because reworking things seems to be a lot more work. How we want to export this to user space is another matter.

One suggestion is to a have /proc or a proc like filesystem that allows us to read, create, and populate files to see all of the application state. Then in userspace it is possible that the transfer of the checkpoint would be as simple as rsync.

Ok back to my cave for a bit.

Eric

Containers mailing list

Containers@lists.linux-foundation.org

https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: Re: [RFC][PATCH 4/4] PID: use the target ID specified in procfs Posted by Nadia Derbey on Thu, 13 Mar 2008 10:41:40 GMT View Forum Message <> Reply to Message

```
Eric W. Biederman wrote:
> "Nadia Derbey" <Nadia.Derbey@bull.net> writes:
>>A couple of weeks ago, a discussion has started after Pierre's proposal for
>>a new syscall to change an ipc id (see thread
>>http://lkml.org/lkml/2008/1/29/209).
>>
>>
>>Oren's suggestion was to force an object's id during its creation, rather
>>than 1. create it, 2. change its id.
>>So here is an implementation of what Oren has suggested.
>>
>>2 new files are defined under /proc/self:
>> . next_ipcid --> next id to use for ipc object creation
>> . next_pids --> next upid nr(s) to use for next task to be forked
              (see patch #2 for more details).
>>
>>
>>When one of these files (or both of them) is filled, a structure pointed to
>>by the calling task struct is filled with these ids.
>>
>>Then, when the object is created, the id(s) present in that structure are
>>used. instead of the default ones.
>>A couple of weeks ago, a discussion has started after Pierre's proposal for
>>a new syscall to change an ipc id (see thread
>>http://lkml.org/lkml/2008/1/29/209).
>>
>>
>>Oren's suggestion was to force an object's id during its creation, rather
>>than 1. create it, 2. change its id.
>>
>>So here is an implementation of what Oren has suggested.
>>2 new files are defined under /proc/self:
>> . next_ipcid --> next id to use for ipc object creation
>> . next_pids --> next upid nr(s) to use for next task to be forked
              (see patch #2 for more details).
>>
```

>> >>When one of these files (or both of them) is filled, a structure pointed to >>by the calling task struct is filled with these ids. >> >>Then, when the object is created, the id(s) present in that structure are >>used, instead of the default ones. > > "Serge E. Hallyn" <serue@us.ibm.com> writes: > > >>Right the alloc pidmap() changes will probably be pretty much the same >>no matter how we do set\_it(), so it's worth discussing. But I'm >>particularly curious to see what opinions are on the sys\_setid(). > > A couple of comments. With respect to alloc pidmap we already have > the necessary controls (a minimum and a maximum) in place for the > allocation. So except for double checking that those controls are exported > in /proc/sys we don't necessarily need to do anything, special. > Just play games with the minimum pid value before you fork.

Excellent idea! It's trus that properly setting things, we can make the loops executed only once in case we want to use a predefined id.

Second at least to get the memory map correct we need additional
kernel support.
Third to actually get the values out it appears we need additional kernel
support as well. From my limited playing with these things at least
parts of the code were easier to implement in the kernel. The hoops
you have to go to restore a single process (without threads) are
absolutely horrendous in user space.

Ok, but if we have a process that belongs to nested namepsaces, we have no other choice than provide its upid nrs hierarchy, right? So, I guess it's more the way it is presented that you don't agree with (of course provided that we are in a user space oriented solution)?

> So this patchset whether it is setid or setting the id at creation time > seems to be jumping the gun. For some namespaces renames are valid and > we can support them. For other namespaces setting the id is a big no-no, > and possibly even controlling the id at creation time is a problem (at > least in the general sense).

I'm sorry but I'm pretty new in this domain, so I don't see what are the namespaces where setting (or pre-setting) the id would be a problem?

- > Because if you can easily control the id
- > you may be able to more easily exploit security holes.

>

- > I'm not at all inclined to make it easy for userspace to rename or set
- > the id of a new resource unless it already makes sense in that
- > namespace.

>

- > We need to limit anything in a checkpoint to user space visible
- > state.

OK, but a tasks that belongs to nested pid namespaces is known from other tasks as one of its "intermediate" pids, depending on the namespace level we are considering. So we can consider these "intermediate pids" as user space visible, can't we?

Given the following pid namespaces hierarchy: PNS0 -> PNS1 -> PNS2 -> PNS3 -> PNS4 A task that belongs to PSN2 has 3 upid nrs: UP0, UP1, and UP2

So:

- . UP0 can be obtained if we do a "ps -ef" in pid ns #1 (PNS0)
- . UP1 can be obtained if we do a "ps -ef" in pid ns #1 (PNS1)
- . UP2 can be obtained if we do a "ps -ef" in pid ns #1 (PNS2)

So UP[0-2] are user space visible (again, depending on "where" we are in pid ns hierarchy, aren't they?

- > For sockets this can get fairly abstract since on the wire
- > state of a tcp socket is in some sense user visible. However it
- > should not include things that user space can never see like socket
- > hash values.

>

- > Partly what this set of patches demonstrates is that it is fairly
- > straight forward to restore ids. Getting the little details of the
- > proper maintainable user space interface correct is harder.

>

- > The goal with any userspace implementation is to that we can separate
- > policy form mechanism. So what are the trade offs for various
- > approaches.

- > At least for inspection at the checkpoint side it would be nice for
- > debugging applications to easily get at all of the user space visible
- > state. So there is an argument for making state that is only
- > indirectly visible, visible for diagnostic and debugging purposes.

>

> For saving the state to disk it appears we need to stop all of the

- > processes in our container. Again something a debugging application
- > of an entire container may want to do. Although we also want to stop
- > the hardware queues for things like networking so we don't transmit
- > or possibly receive new packets either.

>

- > We want a checkpoint/restart to be essentially atomic, with non
- > of the tasks that we stop being able to prove that they ran while
- > the checkpoint was being taken. Mostly this is an interprocess
- > communication blackout, but there may be more to it then that.

>

- > We want checkpoint/restart if possible to be incremental. So
- > we can perform actions like live migration efficiently if most of
- > the data is not changing.

>

- > So there is an argument to perform the work piecemeal instead of
- > in one big shot. Although if we can load data from wherever
- > into the kernel data structures quickly it may not be a big deal.

>

- > We also want the transfer of state to be fast. Which tends to argue
- > in the other direction. That we want a bulk operation that can save
- > out everything and restore everything quickly.

>

- > We also want a design that we can implement incrementally. So that
- > we can avoid supporting everything at first and if there is state
- > that we should save that we can't (or similarly state that we should
- > restore but we can't) the save/restore fails. Until that part is
- > implemented.

>

- > Further we need to finish difficult things like sysfs support and
- > proc support for simply running applications in containers.

>

- > So while I think it is good to be thinking and playing with these
- > ideas now. I think having a more complete story and not pecking on
- > the pieces right now is important.

Sure, I completely agree with you! So may be the 1st thing to do would be to decide which approach (user space vs kernel) should be adopted for c/r? Sorry if what I'm saying is stupid, but imho a clear answer to this question would make us all go the same direction ==> save time for further investigations.

- > My inclination is that create with a specified set of ids is the
- > proper internal kernel API, so we don't have rework things later,
- > because reworking things seems to be a lot more work.

Completely agree with you: the earlier in the object's life we do it, the best it is ;-)

> How we want to
> export this to user space is another matter.

> One suggestion is to a have /proc or a proc like filesystem that

> allows us to read, create, and populate files to see all of the

> application state.

And that would be quite useful for debugging purpose, as you were saying earlier.

Then in userspace it is possible that thetransfer of the checkpoint would be as simple as rsync.

> Ok back to my cave for a bit.

>

> Eric

>

>

Regards, Nadia

\_\_\_\_\_

Containers mailing list Containers@lists.linux-foundation.org https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: Re: [RFC][PATCH 4/4] PID: use the target ID specified in procfs Posted by ebiederm on Thu, 13 Mar 2008 17:40:01 GMT View Forum Message <> Reply to Message

Nadia Derbey <Nadia.Derbey@bull.net> writes:

```
> Eric W. Biederman wrote:
>> "Nadia Derbey" <Nadia.Derbey@bull.net> writes:
>>
>>>A couple of weeks ago, a discussion has started after Pierre's proposal for
>>>a new syscall to change an ipc id (see thread
>>>http://lkml.org/lkml/2008/1/29/209).
>>>
>>>
>>> by
>>> oren's suggestion was to force an object's id during its creation, rather
>>>than 1. create it, 2. change its id.
```

```
>>>
>>>So here is an implementation of what Oren has suggested.
>>>
>>>2 new files are defined under /proc/self:
>>> . next ipcid --> next id to use for ipc object creation
>>> . next_pids --> next upid nr(s) to use for next task to be forked
               (see patch #2 for more details).
>>>
>>>
>>>When one of these files (or both of them) is filled, a structure pointed to
>>>by the calling task struct is filled with these ids.
>>>
>>>Then, when the object is created, the id(s) present in that structure are
>>>used, instead of the default ones.
>>>A couple of weeks ago, a discussion has started after Pierre's proposal for
>>>a new syscall to change an ipc id (see thread
>>>http://lkml.org/lkml/2008/1/29/209).
>>>
>>>
>>>Oren's suggestion was to force an object's id during its creation, rather
>>>than 1. create it, 2. change its id.
>>>
>>>So here is an implementation of what Oren has suggested.
>>>
>>>2 new files are defined under /proc/self:
>>> . next_ipcid --> next id to use for ipc object creation
>>> . next_pids --> next upid nr(s) to use for next task to be forked
               (see patch #2 for more details).
>>>
>>>
>>>When one of these files (or both of them) is filled, a structure pointed to
>>>by the calling task struct is filled with these ids.
>>>
>>>Then, when the object is created, the id(s) present in that structure are
>>>used, instead of the default ones.
>>
>>
>> "Serge E. Hallyn" <serue@us.ibm.com> writes:
>>
>>
>>>Right the alloc_pidmap() changes will probably be pretty much the same
>>>no matter how we do set_it(), so it's worth discussing. But I'm
>>>particularly curious to see what opinions are on the sys setid().
>>
>>
>> A couple of comments. With respect to alloc_pidmap we already have
>> the necessary controls (a minimum and a maximum) in place for the
>> allocation. So except for double checking that those controls are exported
>> in /proc/sys we don't necessarily need to do anything, special.
>>
```

>> Just play games with the minimum pid value before you fork.
> Excellent idea! It's trus that properly setting things, we can make the loops
> executed only once in case we want to use a predefined id.
>
>> Second at least to get the memory map correct we need additional
>> kernel support.
>>
>> Third to actually get the values out it appears we need additional kernel
>> support as well. From my limited playing with these things at least
>> parts of the code were easier to implement in the kernel. The hoops
>> you have to go to restore a single process (without threads) are

>> absolutely horrendous in user space. >

I was thinking in particular of the mm setup above.

> Ok, but if we have a process that belongs to nested namepsaces, we have no other > choice than provide its upid nrs hierarchy, right?

At least a part of it. You only have to provide as much of the nested pid hiearchy as you are restoring from your checkpoint.

- > So, I guess it's more the way it is presented that you don't agree with (of > course provided that we are in a user space oriented solution)?
- Yes. On the kernel side we are essentially fine.
- >> So this patchset whether it is setid or setting the id at creation time
  >> seems to be jumping the gun. For some namespaces renames are valid and
  >> we can support them. For other namespaces setting the id is a big no-no,
  >> and possibly even controlling the id at creation time is a problem (at
  >> least in the general sense).

>

> I'm sorry but I'm pretty new in this domain, so I don't see what are the > namespaces where setting (or pre-setting) the id would be a problem?

pids to some extent as people use them in all kinds of files. Being able to force the pid of another process could make a hard to trigger security hole with file permissions absolutely trivial to hit.

Changing the pid on a process would be even worse because then how could you send it signals.

I haven't looked close enough to be able to say in situation X it is a problem or in situation Y it is clearly not a problem. I just know

there is a lot that happens with ids and security so we need to tread lightly, and carefully.

- >> Because if you can easily control the id
- >> you may be able to more easily exploit security holes.

>>

- >> I'm not at all inclined to make it easy for userspace to rename or set
- >> the id of a new resource unless it already makes sense in that
- >> namespace.

>>

- >> We need to limit anything in a checkpoint to user space visible
- >> state.

>

- > OK, but a tasks that belongs to nested pid namespaces is known from other tasks
- > as one of its "intermediate" pids, depending on the namespace level we are
- > considering. So we can consider these "intermediate pids" as user space visible,
- > can't we?

## Yes.

- > Given the following pid namespaces hierarchy:
- > PNS0 -> PNS1 -> PNS2 -> PNS3 -> PNS4
- > A task that belongs to PSN2 has 3 upid nrs:
- > UP0, UP1, and UP2
- > So:
- > . UP0 can be obtained if we do a "ps -ef" in pid ns #1 (PNS0)
- > . UP1 can be obtained if we do a "ps -ef" in pid ns #1 (PNS1)
- > . UP2 can be obtained if we do a "ps -ef" in pid ns #1 (PNS2)

>

- > So UP[0-2] are user space visible (again, depending on "where" we are in pid ns
- > hierarchy, aren't they?

## Totally.

- > Sure, I completely agree with you! So may be the 1st thing to do would be to
- > decide which approach (user space vs kernel) should be adopted for c/r? Sorry if
- > what I'm saying is stupid, but imho a clear answer to this question would make
- > us all go the same direction ==> save time for further investigations.

Agreed, although it isn't quite that cut and dry.

The question is what granularity do we export the checkpoint restore functionality with, and do we manage to have it serve additional functions as well.

Because ultimately it is user space saying checkpoint and it is user space saying restore. Although we need to be careful that there are not cheaper migration solutions that we are precluding.

Getting the user space interface correct is going to be the tricky and important.

My inclination is that the cost in migrating a container is the cost of moving the data between machines. Which (not counting filesystems) would be the anonymous pages and the shared memory areas.

So if we have a checkpoint as a directory. We could have files for the data of each shared memory region.

We could have files for the data of each shared anonymous region shared between mm's.

We could have ELF core files with extra notes to describe the full state of each process.

We could have files describing each sysvipc object (shared memory, message queues, and semaphores).

## Futexes?

I would suggest a directory for each different kind of file, making conflicts easier to avoid, and data types easier to predict.

Once we have a least one valid checkpoint format the question becomes how do we get the checkpoint out of the kernel, and how do we get the checkpoint into the kernel. And especially how do we allow for incremental data movement so live migration with minimal interruption of service is possible.

This means that we need to preload all of the large memory areas into shared memory areas or processes. Everything else file descriptors and the like I expect will be sufficiently inexpesive that we can treat their recreation as instantaneous.

If incremental migration of data was not so useful I would say just have a single syscall to dump everything, and another syscall to restore everything.

Since incremental migration is so useful. My gut feel is checkpointfs or something similar where we can repeated read and write a checkpoint before we commit to starting it is useful. I am welcome to other better suggestions from the experience of the people who have implemented this before.

A very fine grained user space solution where user space createsn each object using the traditional APIs and restores them similarly seems harder to implement, harder to get right, and harder to maintain. In part because it hides what we are actually trying to do.

Further a fine grained user space approach appears to offer no advantages when it comes to restoring a checkpoint and incrementally updating it so that the down time between machines is negligible.

- >> My inclination is that create with a specified set of ids is the
- >> proper internal kernel API, so we don't have rework things later,
- >> because reworking things seems to be a lot more work.

>

- > Completely agree with you: the earlier in the object's life we do it, the best
- > it is ;-)

>

- >> How we want to
- >> export this to user space is another matter.

>>

- >> One suggestion is to a have /proc or a proc like filesystem that
- >> allows us to read, create, and populate files to see all of the
- >> application state.

>

- > And that would be quite useful for debugging purpose, as you were saying
- > earlier.

Yes. Part of why I suggested it in that way. Debugging and checkpoint/restart have a lot in common. If we can take advantage of that it would be cool.

Eric

Containers mailing list

Containers@lists.linux-foundation.org

https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: Re: [RFC][PATCH 4/4] PID: use the target ID specified in procfs Posted by serue on Thu, 13 Mar 2008 19:06:57 GMT

View Forum Message <> Reply to Message

Quoting Eric W. Biederman (ebiederm@xmission.com):

> Nadia Derbey <Nadia.Derbey@bull.net> writes:

```
> > Eric W. Biederman wrote:
> >> "Nadia Derbey" <Nadia.Derbey@bull.net> writes:
> >>
>>>A couple of weeks ago, a discussion has started after Pierre's proposal for
>>>a new syscall to change an ipc id (see thread
>>>http://lkml.org/lkml/2008/1/29/209).
> >>>
> >>>
>>>Oren's suggestion was to force an object's id during its creation, rather
>>>than 1. create it, 2. change its id.
>>>So here is an implementation of what Oren has suggested.
> >>>
>>>2 new files are defined under /proc/self:
>>>> . next_ipcid --> next id to use for ipc object creation
>>>> . next_pids --> next upid nr(s) to use for next task to be forked
                 (see patch #2 for more details).
> >>>
> >>>
>>>>When one of these files (or both of them) is filled, a structure pointed to
>>>by the calling task struct is filled with these ids.
>>>>Then, when the object is created, the id(s) present in that structure are
>>>used, instead of the default ones.
>>>A couple of weeks ago, a discussion has started after Pierre's proposal for
>>>a new syscall to change an ipc id (see thread
>>>http://lkml.org/lkml/2008/1/29/209).
> >>>
> >>>
>>>Oren's suggestion was to force an object's id during its creation, rather
>>>than 1. create it, 2. change its id.
> >>>
>>>So here is an implementation of what Oren has suggested.
> >>>
>>>2 new files are defined under /proc/self:
>>>> . next_ipcid --> next id to use for ipc object creation
>>>> . next_pids --> next upid nr(s) to use for next task to be forked
> >>>
                 (see patch #2 for more details).
> >>>
>>>>When one of these files (or both of them) is filled, a structure pointed to
>>>by the calling task struct is filled with these ids.
> >>>
>>>>Then, when the object is created, the id(s) present in that structure are
>>>used, instead of the default ones.
> >>
> >> "Serge E. Hallyn" <serue@us.ibm.com> writes:
> >>
> >>
```

```
>>>>Right the alloc_pidmap() changes will probably be pretty much the same
>>>no matter how we do set it(), so it's worth discussing. But I'm
>>>particularly curious to see what opinions are on the sys_setid().
> >>
> >>
>>> A couple of comments. With respect to alloc_pidmap we already have
>>> the necessary controls (a minimum and a maximum) in place for the
>>> allocation. So except for double checking that those controls are exported
>>> in /proc/sys we don't necessarily need to do anything, special.
> >>
>>> Just play games with the minimum pid value before you fork.
>> Excellent idea! It's trus that properly setting things, we can make the loops
>> executed only once in case we want to use a predefined id.
> >
> >>
>>> Second at least to get the memory map correct we need additional
> >> kernel support.
> >>
> >>
>>> Third to actually get the values out it appears we need additional kernel
>>> support as well. From my limited playing with these things at least
>>> parts of the code were easier to implement in the kernel. The hoops
>>> you have to go to restore a single process (without threads) are
>>> absolutely horrendous in user space.
> >
> I was thinking in particular of the mm setup above.
>
> > Ok, but if we have a process that belongs to nested namepsaces, we have no other
> > choice than provide its upid nrs hierarchy, right?
>
> At least a part of it. You only have to provide as much of the nested
> pid hiearchy as you are restoring from your checkpoint.
>
>> So. I guess it's more the way it is presented that you don't agree with (of
>> course provided that we are in a user space oriented solution)?
>
> Yes. On the kernel side we are essentially fine.
>>> So this patchset whether it is setid or setting the id at creation time
>>> seems to be jumping the gun. For some namespaces renames are valid and
>>> we can support them. For other namespaces setting the id is a big no-no,
>>> and possibly even controlling the id at creation time is a problem (at
> >> least in the general sense).
>> I'm sorry but I'm pretty new in this domain, so I don't see what are the
> > namespaces where setting (or pre-setting) the id would be a problem?
```

```
>
> pids to some extent as people use them in all kinds of files. Being
> able to force the pid of another process could make a hard to trigger
> security hole with file permissions absolutely trivial to hit.
> Changing the pid on a process would be even worse because then how
> could you send it signals.
> I haven't looked close enough to be able to say in situation X it is a
> problem or in situation Y it is clearly not a problem. I just know
> there is a lot that happens with ids and security so we need to tread
> lightly, and carefully.
>
>>> Because if you can easily control the id
>>> you may be able to more easily exploit security holes.
> >>
>>> I'm not at all inclined to make it easy for userspace to rename or set
>>> the id of a new resource unless it already makes sense in that
>>> namespace.
>>> We need to limit anything in a checkpoint to user space visible
> >> state.
> >
> > OK, but a tasks that belongs to nested pid namespaces is known from other tasks
> > as one of its "intermediate" pids, depending on the namespace level we are
>> considering. So we can consider these "intermediate pids" as user space visible.
> > can't we?
> Yes.
> > Given the following pid namespaces hierarchy:
> > PNS0 -> PNS1 -> PNS2 -> PNS3 -> PNS4
> > A task that belongs to PSN2 has 3 upid nrs:
> > UP0, UP1, and UP2
> > So:
>> . UP0 can be obtained if we do a "ps -ef" in pid ns #1 (PNS0)
>> . UP1 can be obtained if we do a "ps -ef" in pid ns #1 (PNS1)
>> . UP2 can be obtained if we do a "ps -ef" in pid ns #1 (PNS2)
>> So UP[0-2] are user space visible (again, depending on "where" we are in pid ns
> > hierarchy, aren't they?
>
> Totally.
>
>> Sure, I completely agree with you! So may be the 1st thing to do would be to
> > decide which approach (user space vs kernel) should be adopted for c/r? Sorry if
> > what I'm saying is stupid, but imho a clear answer to this guestion would make
>> us all go the same direction ==> save time for further investigations.
```

```
> Agreed, although it isn't quite that cut and dry.
> The question is what granularity do we export the checkpoint restore
> functionality with, and do we manage to have it serve additional
> functions as well.
> Because ultimately it is user space saying checkpoint and it is user
> space saying restore. Although we need to be careful that there
> are not cheaper migration solutions that we are precluding.
> Getting the user space interface correct is going to be the tricky
> and important.
>
>
>
> My inclination is that the cost in migrating a container is the cost
> of moving the data between machines. Which (not counting filesystems)
> would be the anonymous pages and the shared memory areas.
I'm playing around with providing swapfile namespaces. An app expecting
to be checkpointed could start itself with unshare (CLONE NEWSWAP), and
would receive an empty swapfile ns. Then it could swapon some nfs
mounted file. When it though time for migration might be coming up, it
could ask to swap out more of it's unused memory ahead of time to speed
up the actual checkpoint. Finally, the checkpoing would be swapping out
all the remaining pages, writing the pte info to a file (Dave has
mentioned and played with this), and then suspending the rest of the
kernel resources.
> So if we have a checkpoint as a directory.
> We could have files for the data of each shared memory region.
> We could have files for the data of each shared anonymous region
> shared between mm's.
> We could have ELF core files with extra notes to describe the full
> state of each process.
> We could have files describing each sysvipc object (shared memory,
> message queues, and semaphores).
> Futexes?
>
> I would suggest a directory for each different kind of file, making
```

> >

> conflicts easier to avoid, and data types easier to predict.

> Once we have a least one valid checkpoint format the question becomes > how do we get the checkpoint out of the kernel, and how do we get > the checkpoint into the kernel. And especially how do we allow for > incremental data movement so live migration with minimal interruption > of service is possible. > This means that we need to preload all of the large memory areas into > shared memory areas or processes. Everything else file descriptors > and the like I expect will be sufficiently inexpesive that we can > treat their recreation as instantaneous. > If incremental migration of data was not so useful I would say just > have a single syscall to dump everything, and another syscall to > restore everything. > > Since incremental migration is so useful. My gut feel is > checkpointfs or something similar where we can repeated read > and write a checkpoint before we commit to starting it is useful. > I am welcome to other better suggestions from the experience of the > people who have implemented this before. > > > A very fine grained user space solution where user space createsn > each object using the traditional APIs and restores them similarly > seems harder to implement, harder to get right, and harder to > maintain. In part because it hides what we are actually trying to do. > > Further a fine grained user space approach appears to offer no > advantages when it comes to restoring a checkpoint and incrementally > updating it so that the down time between machines is negligible. >>> My inclination is that create with a specified set of ids is the >>> proper internal kernel API, so we don't have rework things later, > >> because reworking things seems to be a lot more work. >> Completely agree with you: the earlier in the object's life we do it, the best > > it is ;-) > >> How we want to >>> export this to user space is another matter. >>> One suggestion is to a have /proc or a proc like filesystem that >>> allows us to read, create, and populate files to see all of the >>> application state. > > >> And that would be quite useful for debugging purpose, as you were saying

```
> > earlier.
> 
> Yes. Part of why I suggested it in that way. Debugging and
> checkpoint/restart have a lot in common. If we can take advantage of
> that it would be cool.
> 
> Eric

Containers mailing list
Containers@lists.linux-foundation.org
https://lists.linux-foundation.org/mailman/listinfo/containers
```

Subject: Re: [RFC][PATCH 4/4] PID: use the target ID specified in procfs Posted by Oren Laadan on Thu, 13 Mar 2008 20:01:02 GMT View Forum Message <> Reply to Message

```
Eric W. Biederman wrote:
> Nadia Derbey < Nadia. Derbey @bull.net > writes:
>> Eric W. Biederman wrote:
>>> "Nadia Derbey" <Nadia.Derbey@bull.net> writes:
>>>
>>>> A couple of weeks ago, a discussion has started after Pierre's proposal for
>>>> a new syscall to change an ipc id (see thread
>>> http://lkml.org/lkml/2008/1/29/209).
>>>>
>>> Oren's suggestion was to force an object's id during its creation, rather
>>>> than 1. create it, 2. change its id.
>>>> So here is an implementation of what Oren has suggested.
>>>>
>>>> 2 new files are defined under /proc/self:
>>>> . next ipcid --> next id to use for ipc object creation
>>> . next_pids --> next upid nr(s) to use for next task to be forked
                (see patch #2 for more details).
>>>>
>>>>
>>>> When one of these files (or both of them) is filled, a structure pointed to
>>>> by the calling task struct is filled with these ids.
>>>> Then, when the object is created, the id(s) present in that structure are
>>> used, instead of the default ones.
>>>> A couple of weeks ago, a discussion has started after Pierre's proposal for
>>> a new syscall to change an ipc id (see thread
>>> http://lkml.org/lkml/2008/1/29/209).
>>>>
>>>>
```

```
>>> Oren's suggestion was to force an object's id during its creation, rather
>>>> than 1. create it, 2. change its id.
>>>>
>>>> So here is an implementation of what Oren has suggested.
>>>>
>>>> 2 new files are defined under /proc/self:
>>> . next ipcid --> next id to use for ipc object creation
>>> . next_pids --> next upid nr(s) to use for next task to be forked
                (see patch #2 for more details).
>>>>
>>>>
>>>> When one of these files (or both of them) is filled, a structure pointed to
>>>> by the calling task struct is filled with these ids.
>>>>
>>>> Then, when the object is created, the id(s) present in that structure are
>>> used, instead of the default ones.
>>>
>>> "Serge E. Hallyn" <serue@us.ibm.com> writes:
>>>
>>>
>>>> Right the alloc_pidmap() changes will probably be pretty much the same
>>> no matter how we do set_it(), so it's worth discussing. But I'm
>>> particularly curious to see what opinions are on the sys setid().
>>>
>>> A couple of comments. With respect to alloc_pidmap we already have
>>> the necessary controls (a minimum and a maximum) in place for the
>>> allocation. So except for double checking that those controls are exported
>>> in /proc/sys we don't necessarily need to do anything, special.
>>>
>>> Just play games with the minimum pid value before you fork.
>> Excellent idea! It's trus that properly setting things, we can make the loops
>> executed only once in case we want to use a predefined id.
>>
>>> Second at least to get the memory map correct we need additional
>>> kernel support.
>>>
>>>
>>> Third to actually get the values out it appears we need additional kernel
>>> support as well. From my limited playing with these things at least
>>> parts of the code were easier to implement in the kernel. The hoops
>>> you have to go to restore a single process (without threads) are
>>> absolutely horrendous in user space.
> I was thinking in particular of the mm setup above.
>
>> Ok, but if we have a process that belongs to nested namepsaces, we have no other
>> choice than provide its upid nrs hierarchy, right?
> At least a part of it. You only have to provide as much of the nested
```

> pid hiearchy as you are restoring from your checkpoint. >> So, I guess it's more the way it is presented that you don't agree with (of >> course provided that we are in a user space oriented solution)? > Yes. On the kernel side we are essentially fine. >>> So this patchset whether it is setid or setting the id at creation time >>> seems to be jumping the gun. For some namespaces renames are valid and >>> we can support them. For other namespaces setting the id is a big no-no, >>> and possibly even controlling the id at creation time is a problem (at >>> least in the general sense). >> I'm sorry but I'm pretty new in this domain, so I don't see what are the >> namespaces where setting (or pre-setting) the id would be a problem? > pids to some extent as people use them in all kinds of files. Being > able to force the pid of another process could make a hard to trigger > security hole with file permissions absolutely trivial to hit. Since the intent of this mechanism is to allow ckpt/restart, it makes sense to only allow this operation during restart. For example, in zap, containers have a state, e.g. running, stopped, ckpt, restart, and this is only possible in restart state; Furthermore, a container can only be put in restart state at creation time, and only by root. Of course, you should only trust that as much as you trust the root :O

> Changing the pid on a process would be even worse because then how > could you send it signals.
> I haven't looked close enough to be able to say in situation X it is a > problem or in situation Y it is clearly not a problem. I just know > there is a lot that happens with ids and security so we need to tread > lightly, and carefully.
> >>> Because if you can easily control the id >>> you may be able to more easily exploit security holes.
>>> | I'm not at all inclined to make it easy for userspace to rename or set >>> the id of a new resource unless it already makes sense in that

>>> namespace.
>>>

>>> We need to limit anything in a checkpoint to user space visible >>> state.

>> OK, but a tasks that belongs to nested pid namespaces is known from other tasks >> as one of its "intermediate" pids, depending on the namespace level we are >> considering. So we can consider these "intermediate pids" as user space visible, >> can't we?

```
>
> Yes.
>> Given the following pid namespaces hierarchy:
>> PNS0 -> PNS1 -> PNS2 -> PNS3 -> PNS4
>> A task that belongs to PSN2 has 3 upid nrs:
>> UP0, UP1, and UP2
>> So:
>> . UP0 can be obtained if we do a "ps -ef" in pid ns #1 (PNS0)
>> . UP1 can be obtained if we do a "ps -ef" in pid ns #1 (PNS1)
>> . UP2 can be obtained if we do a "ps -ef" in pid ns #1 (PNS2)
>>
>> So UP[0-2] are user space visible (again, depending on "where" we are in pid ns
>> hierarchy, aren't they?
> Totally.
>> Sure, I completely agree with you! So may be the 1st thing to do would be to
>> decide which approach (user space vs kernel) should be adopted for c/r? Sorry if
>> what I'm saying is stupid, but imho a clear answer to this question would make
>> us all go the same direction ==> save time for further investigations.
> Agreed, although it isn't quite that cut and dry.
> The question is what granularity do we export the checkpoint restore
> functionality with, and do we manage to have it serve additional
> functions as well.
> Because ultimately it is user space saying checkpoint and it is user
> space saying restore. Although we need to be careful that there
> are not cheaper migration solutions that we are precluding.
>
> Getting the user space interface correct is going to be the tricky
> and important.
>
>
> My inclination is that the cost in migrating a container is the cost
> of moving the data between machines. Which (not counting filesystems)
> would be the anonymous pages and the shared memory areas.
> So if we have a checkpoint as a directory.
> We could have files for the data of each shared memory region.
>
> We could have files for the data of each shared anonymous region
> shared between mm's.
> We could have ELF core files with extra notes to describe the full
```

> state of each process. > We could have files describing each sysvipc object (shared memory, > message queues, and semaphores). > Futexes? > I would suggest a directory for each different kind of file, making > conflicts easier to avoid, and data types easier to predict. > > > Once we have a least one valid checkpoint format the question becomes > how do we get the checkpoint out of the kernel, and how do we get > the checkpoint into the kernel. And especially how do we allow for > incremental data movement so live migration with minimal interruption > of service is possible. > This means that we need to preload all of the large memory areas into > shared memory areas or processes. Everything else file descriptors > and the like I expect will be sufficiently inexpesive that we can > treat their recreation as instantaneous. > If incremental migration of data was not so useful I would say just > have a single syscall to dump everything, and another syscall to > restore everything. > > Since incremental migration is so useful. My gut feel is > checkpointfs or something similar where we can repeated read > and write a checkpoint before we commit to starting it is useful. > I am welcome to other better suggestions from the experience of the > people who have implemented this before. > > A very fine grained user space solution where user space createsn > each object using the traditional APIs and restores them similarly > seems harder to implement, harder to get right, and harder to > maintain. In part because it hides what we are actually trying to do. > Further a fine grained user space approach appears to offer no > advantages when it comes to restoring a checkpoint and incrementally > updating it so that the down time between machines is negligible. > >>> My inclination is that create with a specified set of ids is the >>> proper internal kernel API, so we don't have rework things later, >>> because reworking things seems to be a lot more work. >> Completely agree with you: the earlier in the object's life we do it, the best

```
>> it is ;-)
>>
>>> How we want to
>>> export this to user space is another matter.
>>>
>>> One suggestion is to a have /proc or a proc like filesystem that
>>> allows us to read, create, and populate files to see all of the
>>> application state.
>> And that would be guite useful for debugging purpose, as you were saying
>> earlier.
> Yes. Part of why I suggested it in that way. Debugging and
> checkpoint/restart have a lot in common. If we can take advantage of
> that it would be cool.
> Eric
> Containers mailing list
> Containers@lists.linux-foundation.org
> https://lists.linux-foundation.org/mailman/listinfo/containers
Containers mailing list
```

Subject: Re: [RFC][PATCH 4/4] PID: use the target ID specified in procfs Posted by ebiederm on Thu, 13 Mar 2008 23:12:40 GMT

View Forum Message <> Reply to Message

Containers@lists.linux-foundation.org

Oren Laadan <orenl@cs.columbia.edu> writes:

>>> I'm sorry but I'm pretty new in this domain, so I don't see what are the >>> namespaces where setting (or pre-setting) the id would be a problem?

>> pids to some extent as people use them in all kinds of files. Being

>> able to force the pid of another process could make a hard to trigger

>> security hole with file permissions absolutely trivial to hit.

https://lists.linux-foundation.org/mailman/listinfo/containers

> Since the intent of this mechanism is to allow ckpt/restart, it makes

- > sense to only allow this operation during restart. For example, in zap,
- > containers have a state, e.g. running, stopped, ckpt, restart, and this
- > is only possible in restart state; Furthermore, a container can only be
- > put in restart state at creation time, and only by root. Of course, you
- > should only trust that as much as you trust the root :O

Yes and thanks.

>

The notion of the state of a container makes a lot of sense (even if we never implement explicit state bits).

#### Eric

Containers mailing list
Containers@lists.linux-foundation.org
https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id Posted by Oren Laadan on Thu, 13 Mar 2008 23:16:07 GMT View Forum Message <> Reply to Message

Nadia.Derbey@bull.net wrote:

- > A couple of weeks ago, a discussion has started after Pierre's proposal for
- > a new syscall to change an ipc id (see thread
- > http://lkml.org/lkml/2008/1/29/209).

> >

- > Oren's suggestion was to force an object's id during its creation, rather
- > than 1. create it, 2. change its id.

>

> So here is an implementation of what Oren has suggested.

>

- > 2 new files are defined under /proc/self:
- > . next\_ipcid --> next id to use for ipc object creation
- > . next\_pids --> next upid nr(s) to use for next task to be forked
- > (see patch #2 for more details).

Generally looks good. One meta-comment, though:

I wonder why you use separate files for separate resources, and why you'd want to write multiple identifiers in one go; it seems to complicate the code and interface with minimal gain.

In practice, a process will only do either one or the other, so a single file is enough (e.g. "next\_id").

Also, writing a single value at a time followed by the syscall is enough; it's definitely not a performance issue to have multiple calls.

We assume the user/caller knows what she's doing, so no need to classify the identifier (that is, tell the kernel it's a pid, or an ipc id) ahead of time. The caller simply writes a value and then calls the relevant syscall, or otherwise the results may not be what she expected... If such context is expected to be required (although I don't see any at the moment), we can require that the user write "TYPE VALUE" pair to the "next\_id" file.

>

> When one of these files (or both of them) is filled, a structure pointed to > by the calling task struct is filled with these ids. > Then, when the object is created, the id(s) present in that structure are > used, instead of the default ones. > The patches are against 2.6.25-rc3-mm1, in the following order: > [PATCH 1/4] adds the proofs facility for next ipc to be created. > [PATCH 2/4] adds the proofs facility for next task to be forked. > [PATCH 3/4] makes use of the specified id (if any) to allocate the new IPC object (changes the ipc\_addid() path). > [PATCH 4/4] uses the specified id(s) (if any) to set the upid nr(s) for a newly allocated process (changes the alloc\_pid()/alloc\_pidmap() paths). > > Any comment and/or suggestions are welcome. > Cc-ing Pavel and Sukadev, since they are the pid namespace authors. > Regards, > Nadia > Containers mailing list Containers@lists.linux-foundation.org

Subject: Re: [RFC][PATCH 4/4] PID: use the target ID specified in procfs Posted by Oren Laadan on Thu, 13 Mar 2008 23:24:10 GMT

View Forum Message <> Reply to Message

Eric W. Biederman wrote:

> Oren Laadan <orenl@cs.columbia.edu> writes:

https://lists.linux-foundation.org/mailman/listinfo/containers

>>>> I'm sorry but I'm pretty new in this domain, so I don't see what are the >>> namespaces where setting (or pre-setting) the id would be a problem? >>> pids to some extent as people use them in all kinds of files. Being >>> able to force the pid of another process could make a hard to trigger >>> security hole with file permissions absolutely trivial to hit. >> Since the intent of this mechanism is to allow ckpt/restart, it makes >> sense to only allow this operation during restart. For example, in zap, >> containers have a state, e.g. running, stopped, ckpt, restart, and this >> is only possible in restart state; Furthermore, a container can only be >> put in restart state at creation time, and only by root. Of course, you

>> should only trust that as much as you trust the root :O
>
> Yes and thanks.
>
> The notion of the state of a container makes a lot of sense (even if > we never implement explicit state bits).

I found it extremely helpful in managing containers (pods) in zap. There are three more states, actually: stopping, reviving and dead. It is like extending the notion of process state into their collective representation which is the container. In fact, restricting certain operations to specific states was instrumental in eliminating a myriad of potential races in the implementation.

I believe this belongs to the ever-pending ckpt/restart discussion :)

Oren.

>

> Eric

Containore mailing list

Containers mailing list

Containers@lists.linux-foundation.org

https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id Posted by Nadia Derbey on Fri, 14 Mar 2008 06:21:15 GMT View Forum Message <> Reply to Message

Oren Laadan wrote:

>

> Nadia.Derbey@bull.net wrote:

>

- >> A couple of weeks ago, a discussion has started after Pierre's
- >> proposal for
- >> a new syscall to change an ipc id (see thread
- >> http://lkml.org/lkml/2008/1/29/209).

>>

>>

- >> Oren's suggestion was to force an object's id during its creation, rather
- >> than 1. create it, 2. change its id.

>>

>> So here is an implementation of what Oren has suggested.

>>

- >> 2 new files are defined under /proc/self:
- >> . next\_ipcid --> next id to use for ipc object creation

```
    >> . next_pids --> next upid nr(s) to use for next task to be forked
    >> (see patch #2 for more details).
    >
    > Generally looks good. One meta-comment, though:
    > I wonder why you use separate files for separate resources.
```

That would be needed in a situation wheere we don't care about next, say, ipc id to be created but we need a predefined pid. But I must admit I don't see any pratical application to it.

- > and why you'd
- > want to write multiple identifiers in one go;

I used multiple identifiers only for the pid values: this is because when a new pid value is allocated for a process that belongs to nested namespaces, the lower level upid nr values are allocated in a single shot. (see alloc\_pid()).

- > it seems to complicate the
- > code and interface with minimal gain.
- > In practice, a process will only do either one or the other, so a single
- > file is enough (e.g. "next\_id").
- > Also, writing a single value at a time followed by the syscall is enough;
- > it's definitely not a performance issue to have multiple calls.
- > We assume the user/caller knows what she's doing, so no need to classify
- > the identifier (that is, tell the kernel it's a pid, or an ipc id) ahead
- > of time. The caller simply writes a value and then calls the relevant
- > syscall, or otherwise the results may not be what she expected...
- > If such context is expected to be required (although I don't see any at
- > the moment), we can require that the user write "TYPE VALUE" pair to
- > the "next id" file.

That's exactly what I wanted to avoid by creating 1 file per object. Now, it's true that in a restart context where I guess that things will be done synchronously, we could have a single next\_id file.

```
>> When one of these files (or both of them) is filled, a structure >> pointed to >> by the calling task struct is filled with these ids. >> Then, when the object is created, the id(s) present in that structure are >> used, instead of the default ones. >> The patches are against 2.6.25-rc3-mm1, in the following order:
```

```
>>
>> [PATCH 1/4] adds the proofs facility for next ipc to be created.
>> [PATCH 2/4] adds the proofs facility for next task to be forked.
>> [PATCH 3/4] makes use of the specified id (if any) to allocate the new
>> IPC
>>
          object (changes the ipc_addid() path).
>> [PATCH 4/4] uses the specified id(s) (if any) to set the upid nr(s)
>> for a newly
          allocated process (changes the alloc pid()/alloc pidmap()
>>
>> paths).
>>
>> Any comment and/or suggestions are welcome.
>> Cc-ing Pavel and Sukadev, since they are the pid namespace authors.
>>
>> Regards,
>> Nadia
>>
>> --
>>
>> --
>
Regards,
Nadia
Containers mailing list
Containers@lists.linux-foundation.org
```

Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id Posted by Oren Laadan on Fri, 14 Mar 2008 15:50:13 GMT

View Forum Message <> Reply to Message

```
Nadia Derbey wrote:
> Oren Laadan wrote:
>>
>>
>> Nadia.Derbey@bull.net wrote:
>>
>>> A couple of weeks ago, a discussion has started after Pierre's
>>> proposal for
>>> a new syscall to change an ipc id (see thread
>>> http://lkml.org/lkml/2008/1/29/209).
```

https://lists.linux-foundation.org/mailman/listinfo/containers

```
>>>
>>>
>>> Oren's suggestion was to force an object's id during its creation,
>>> rather
>>> than 1. create it, 2. change its id.
>>>
>>> So here is an implementation of what Oren has suggested.
>>>
>>> 2 new files are defined under /proc/self:
    . next ipcid --> next id to use for ipc object creation
     . next_pids --> next upid nr(s) to use for next task to be forked
                (see patch #2 for more details).
>>>
>>
>>
>> Generally looks good. One meta-comment, though:
>> I wonder why you use separate files for separate resources.
> That would be needed in a situation wheere we don't care about next,
> say, ipc id to be created but we need a predefined pid. But I must admit
> I don't see any pratical application to it.
exactly; why set the next-ipc value so far in advance? I think it's
better (and less confusing) if we require that setting the next-id value
be done right before the respective syscall.
>> and why you'd
>> want to write multiple identifiers in one go;
> I used multiple identifiers only for the pid values: this is because
> when a new pid value is allocated for a process that belongs to nested
> namespaces, the lower level upid nr values are allocated in a single
> shot. (see alloc_pid()).
>
>> it seems to complicate the
>> code and interface with minimal gain.
>> In practice, a process will only do either one or the other, so a single
>> file is enough (e.g. "next_id").
>> Also, writing a single value at a time followed by the syscall is enough;
>> it's definitely not a performance issue to have multiple calls.
>> We assume the user/caller knows what she's doing, so no need to classify
>> the identifier (that is, tell the kernel it's a pid, or an ipc id) ahead
>> of time. The caller simply writes a value and then calls the relevant
>> syscall, or otherwise the results may not be what she expected...
>> If such context is expected to be required (although I don't see any at
>> the moment), we can require that the user write "TYPE VALUE" pair to
>> the "next id" file.
```

```
>
> That's exactly what I wanted to avoid by creating 1 file per object.
> Now, it's true that in a restart context where I guess that things will
> be done synchronously, we could have a single next_id file.
>
>>
>>>
>>> When one of these files (or both of them) is filled, a structure
>>> pointed to
>>> by the calling task struct is filled with these ids.
>>>
>>> Then, when the object is created, the id(s) present in that structure
>>> are
>>> used, instead of the default ones.
>>>
>>> The patches are against 2.6.25-rc3-mm1, in the following order:
>>>
>>> [PATCH 1/4] adds the procfs facility for next ipc to be created.
>>> [PATCH 2/4] adds the procfs facility for next task to be forked.
>>> [PATCH 3/4] makes use of the specified id (if any) to allocate the
>>> new IPC
            object (changes the ipc addid() path).
>>>
>>> [PATCH 4/4] uses the specified id(s) (if any) to set the upid nr(s)
>>> for a newly
>>>
            allocated process (changes the alloc_pid()/alloc_pidmap()
>>> paths).
>>>
>>> Any comment and/or suggestions are welcome.
>>>
>>> Cc-ing Pavel and Sukadev, since they are the pid namespace authors.
>>> Regards,
>>> Nadia
>>>
>>> --
>>>
>>> --
>>
>>
>>
>
> Regards.
> Nadia
Containers mailing list
Containers@lists.linux-foundation.org
```

https://lists.linux-foundation.org/mailman/listinfo/containers

# Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id Posted by Pavel Emelianov on Fri, 14 Mar 2008 15:56:49 GMT

View Forum Message <> Reply to Message

```
Oren Laadan wrote:
> Nadia Derbey wrote:
>> Oren Laadan wrote:
>>> Nadia.Derbey@bull.net wrote:
>>>
>>>> A couple of weeks ago, a discussion has started after Pierre's
>>>> proposal for
>>>> a new syscall to change an ipc id (see thread
>>> http://lkml.org/lkml/2008/1/29/209).
>>>>
>>>>
>>> Oren's suggestion was to force an object's id during its creation,
>>>> rather
>>>> than 1. create it, 2. change its id.
>>>> So here is an implementation of what Oren has suggested.
>>>> 2 new files are defined under /proc/self:
>>>> . next ipcid --> next id to use for ipc object creation
>>> . next pids --> next upid nr(s) to use for next task to be forked
                 (see patch #2 for more details).
>>>>
>>>
>>> Generally looks good. One meta-comment, though:
>>> I wonder why you use separate files for separate resources.
>> That would be needed in a situation wheere we don't care about next,
>> say, ipc id to be created but we need a predefined pid. But I must admit
>> I don't see any pratical application to it.
>
> exactly; why set the next-ipc value so far in advance? I think it's
> better (and less confusing) if we require that setting the next-id value
> be done right before the respective syscall.
And race with some other syscall caller? This will only work if the next-ipc-id
and the next-pid are on a task_struct. Are they (at least supposed to be such)?
Containers mailing list
Containers@lists.linux-foundation.org
https://lists.linux-foundation.org/mailman/listinfo/containers
```

Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id

### Posted by Oren Laadan on Fri, 14 Mar 2008 16:02:46 GMT

View Forum Message <> Reply to Message

Pavel Emelyanov wrote:  > Oren Laadan wrote:  >> Nadia Derbey wrote:  >>> Oren Laadan wrote:  >>> Nadia.Derbey@bull.net wrote:  >>>>
>>>> A couple of weeks ago, a discussion has started after Pierre's >>>> proposal for >>>> a new syscall to change an ipc id (see thread >>>> http://lkml.org/lkml/2008/1/29/209). >>>>
>>>> >>>> Oren's suggestion was to force an object's id during its creation, >>>> rather >>>> than 1. create it, 2. change its id. >>>> >>>> So here is an implementation of what Oren has suggested.
>>>> >>>> >>>> 2 new files are defined under /proc/self: >>>> . next_ipcid> next id to use for ipc object creation >>>> . next_pids> next upid nr(s) to use for next task to be forked >>>> (see patch #2 for more details). >>>> Generally looks good. One meta-comment, though:
>>>> I wonder why you use separate files for separate resources, >>> That would be needed in a situation wheere we don't care about next, >>> say, ipc id to be created but we need a predefined pid. But I must admit >>> I don't see any pratical application to it. >> exactly; why set the next-ipc value so far in advance? I think it's >> better (and less confusing) if we require that setting the next-id value >> be done right before the respective syscall.
> And race with some other syscall caller? This will only work if the next-ipc-id > and the next-pid are on a task_struct. Are they (at least supposed to be such)?
yes. that's the first detail I looked for in the patch :)  Containers mailing list
Containers@lists.linux-foundation.org https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id Posted by Pavel Emelianov on Fri, 14 Mar 2008 16:08:38 GMT

```
Oren Laadan wrote:
> Pavel Emelvanov wrote:
>> Oren Laadan wrote:
>>> Nadia Derbey wrote:
>>> Oren Laadan wrote:
>>>> Nadia.Derbey@bull.net wrote:
>>>> A couple of weeks ago, a discussion has started after Pierre's
>>>> proposal for
>>>>> a new syscall to change an ipc id (see thread
>>>> http://lkml.org/lkml/2008/1/29/209).
>>>>>
>>>>>
>>>> Oren's suggestion was to force an object's id during its creation,
>>>> rather
>>>>> than 1. create it, 2. change its id.
>>>>>
>>>> So here is an implementation of what Oren has suggested.
>>>>>
>>>>> 2 new files are defined under /proc/self:
>>>>> . next ipcid --> next id to use for ipc object creation
>>>>> . next_pids --> next upid nr(s) to use for next task to be forked
                   (see patch #2 for more details).
>>>> Generally looks good. One meta-comment, though:
>>>>
>>>> I wonder why you use separate files for separate resources,
>>>> That would be needed in a situation wheere we don't care about next,
>>> say, ipc id to be created but we need a predefined pid. But I must admit
>>>> I don't see any pratical application to it.
>>> exactly; why set the next-ipc value so far in advance? I think it's
>>> better (and less confusing) if we require that setting the next-id value
>>> be done right before the respective syscall.
>> And race with some other syscall caller? This will only work if the next-ipc-id
>> and the next-pid are on a task_struct. Are they (at least supposed to be such)?
> yes. that's the first detail I looked for in the patch :)
OK:) I just remembered some talks about using last_pid for pid allocations
and just wanted to be sure.
Containers mailing list
Containers@lists.linux-foundation.org
https://lists.linux-foundation.org/mailman/listinfo/containers
```

## Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id Posted by Nadia Derbey on Fri, 14 Mar 2008 16:11:22 GMT

```
Oren Laadan wrote:
> Nadia Derbey wrote:
>> Oren Laadan wrote:
>>
>>>
>>>
>>> Nadia.Derbey@bull.net wrote:
>>>> A couple of weeks ago, a discussion has started after Pierre's
>>>> proposal for
>>>> a new syscall to change an ipc id (see thread
>>> http://lkml.org/lkml/2008/1/29/209).
>>>>
>>>>
>>> Oren's suggestion was to force an object's id during its creation,
>>>> rather
>>>> than 1. create it, 2. change its id.
>>>>
>>>> So here is an implementation of what Oren has suggested.
>>>> 2 new files are defined under /proc/self:
>>>> . next_ipcid --> next id to use for ipc object creation
>>>> . next_pids --> next upid nr(s) to use for next task to be forked
                 (see patch #2 for more details).
>>>>
>>>
>>>
>>> Generally looks good. One meta-comment, though:
>>> I wonder why you use separate files for separate resources,
>>
>>
>> That would be needed in a situation wheere we don't care about next.
>> say, ipc id to be created but we need a predefined pid. But I must
>> admit I don't see any pratical application to it.
>
> exactly; why set the next-ipc value so far in advance? I think it's
> better (and less confusing) if we require that setting the next-id value
> be done right before the respective syscall.
Ok, but this "requirement" should be widely agreed upon ;-)
```

What I mean here is that the solution with 1 file per "object type" can easily be extended imho:

I don't know how the restart is supposed to work, but we can imagine feeding all these files with all the object ids just before restart and let the process pick up the objects ids as it needs them.

Of course, this would require to enhance the files formats, as well as the way things are stored in the task\_struct.

Hope what I'm saying is not too stupid ;-)?

```
Regards,
Nadia
>>
>>> and why you'd
>>> want to write multiple identifiers in one go;
>>
>>
>> I used multiple identifiers only for the pid values: this is because
>> when a new pid value is allocated for a process that belongs to nested
>> namespaces, the lower level upid nr values are allocated in a single
>> shot. (see alloc pid()).
>>
>>> it seems to complicate the
>>> code and interface with minimal gain.
>>> In practice, a process will only do either one or the other, so a single
>>> file is enough (e.g. "next id").
>>> Also, writing a single value at a time followed by the syscall is
>>> enough:
>>> it's definitely not a performance issue to have multiple calls.
>>> We assume the user/caller knows what she's doing, so no need to classify
>>> the identifier (that is, tell the kernel it's a pid, or an ipc id) ahead
>>> of time. The caller simply writes a value and then calls the relevant
>>> syscall, or otherwise the results may not be what she expected...
>>> If such context is expected to be required (although I don't see any at
>>> the moment), we can require that the user write "TYPE VALUE" pair to
>>> the "next id" file.
>>
>>
>> That's exactly what I wanted to avoid by creating 1 file per object.
>> Now, it's true that in a restart context where I guess that things
>> will be done synchronously, we could have a single next_id file.
>>
>>>
>>>>
>>>> When one of these files (or both of them) is filled, a structure
```

```
>>> pointed to
>>>> by the calling task struct is filled with these ids.
>>>>
>>>> Then, when the object is created, the id(s) present in that
>>>> structure are
>>> used, instead of the default ones.
>>>> The patches are against 2.6.25-rc3-mm1, in the following order:
>>>>
>>>> [PATCH 1/4] adds the proofs facility for next ipc to be created.
>>>> [PATCH 2/4] adds the procfs facility for next task to be forked.
>>>> [PATCH 3/4] makes use of the specified id (if any) to allocate the
>>>> new IPC
             object (changes the ipc_addid() path).
>>>>
>>>> [PATCH 4/4] uses the specified id(s) (if any) to set the upid nr(s)
>>>> for a newly
             allocated process (changes the
>>>> alloc_pid()/alloc_pidmap() paths).
>>>>
>>>> Any comment and/or suggestions are welcome.
>>>>
>>>> Cc-ing Pavel and Sukadev, since they are the pid namespace authors.
>>>>
>>>> Regards,
>>>> Nadia
>>>>
>>>> --
>>>>
>>>> --
>>>
>>>
>>>
>>>
>>
>>
>> Regards,
>> Nadia
>
>
```

Containers mailing list Containers@lists.linux-foundation.org https://lists.linux-foundation.org/mailman/listinfo/containers

## Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id Posted by Nadia Derbey on Fri, 14 Mar 2008 16:11:34 GMT

```
Pavel Emelyanov wrote:
> Oren Laadan wrote:
>>Nadia Derbey wrote:
>>>Oren Laadan wrote:
>>>Nadia.Derbey@bull.net wrote:
>>>>
>>>>
>>>>A couple of weeks ago, a discussion has started after Pierre's
>>>>proposal for
>>>>a new syscall to change an ipc id (see thread
>>>>http://lkml.org/lkml/2008/1/29/209).
>>>>
>>>>
>>>>Oren's suggestion was to force an object's id during its creation.
>>>>rather
>>>>than 1. create it, 2. change its id.
>>>>So here is an implementation of what Oren has suggested.
>>>>2 new files are defined under /proc/self:
>>>> . next_ipcid --> next id to use for ipc object creation
>>>> . next pids --> next upid nr(s) to use for next task to be forked
                 (see patch #2 for more details).
>>>>
>>>>
>>> Generally looks good. One meta-comment, though:
>>>I wonder why you use separate files for separate resources,
>>>
>>>That would be needed in a situation wheere we don't care about next,
>>>say, ipc id to be created but we need a predefined pid. But I must admit
>>>I don't see any pratical application to it.
>>exactly: why set the next-ipc value so far in advance? I think it's
>>better (and less confusing) if we require that setting the next-id value
>>be done right before the respective syscall.
>
> And race with some other syscall caller? This will only work if the next-ipc-id
> and the next-pid are on a task_struct. Are they (at least supposed to be such)?
>
```

Yes they are.

Regards, Nadia

\_\_\_\_\_

Containers mailing list

Containers@lists.linux-foundation.org

https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id Posted by Oren Laadan on Fri, 14 Mar 2008 16:45:31 GMT

```
Nadia Derbey wrote:
> Oren Laadan wrote:
>>
>> Nadia Derbey wrote:
>>> Oren Laadan wrote:
>>>
>>>>
>>>>
>>> Nadia.Derbey@bull.net wrote:
>>>> A couple of weeks ago, a discussion has started after Pierre's
>>>> proposal for
>>>> a new syscall to change an ipc id (see thread
>>>> http://lkml.org/lkml/2008/1/29/209).
>>>>
>>>>
>>>> Oren's suggestion was to force an object's id during its creation,
>>>> rather
>>>> than 1. create it, 2. change its id.
>>>>
>>>> So here is an implementation of what Oren has suggested.
>>>> 2 new files are defined under /proc/self:
>>>> . next_ipcid --> next id to use for ipc object creation
       . next pids --> next upid nr(s) to use for next task to be forked
                  (see patch #2 for more details).
>>>>
>>>>
>>>>
>>>>
>>> Generally looks good. One meta-comment, though:
>>>> I wonder why you use separate files for separate resources,
```

```
>>>
>>>
>>>
>>>
>>> That would be needed in a situation wheere we don't care about next,
>>> say, ipc id to be created but we need a predefined pid. But I must
>>> admit I don't see any pratical application to it.
>>>
>>
>>
>> exactly; why set the next-ipc value so far in advance ? I think it's
>> better (and less confusing) if we require that setting the next-id value
>> be done right before the respective syscall.
>
> Ok, but this "requirement" should be widely agreed upon ;-)
```

A discussion on the overall checkpoint/restart policy is certainly due (and increasingly noted recently).

> What I mean here is that the solution with 1 file per "object type" can > easily be extended imho:

I'm aiming at simplicity and minimal (but not restrictive) API for user space. I argue that we never really need more than one predetermined value at a time (eg see below), and the cost of setting such value is so small that there is no real benefit in setting more than one at a time (either via multiple files or via an array of values). If in fact you wanted more than one type at a time, you could still make it happen with a single file without adding many user-visible files in /proc/<pid>.

So far, I can't think of any such identifier that we'd like to pre-set that does not fit into a "long" type; simply because the kernel does not use such identifiers in the first place (pid, ipc, pty#, vc# .. etc). To be on the safe side, we can require that the format be "long VAL", just in case (and later you could have other formats).

The only exception, perhaps, is if a TCP connection is rebuilt with a, say, connect() syscall, and some information needs to be "predetermined" so we'll need to extend the format. That can be done with another type eg. "tcp ....." or a separate file (per your view), \_then\_, not now. (As a side note, I don't suggest that this is how TCP will be restored).

In any event, the bottom line is that a single file, with a single value at a time (possibly annotated with a type), is the simplest, and isn't restrictive, for our purposes. Looking one step ahead, simplicity and minimal commitment to user space is important in trying to push this to the mainline kernel...

> I don't know how the restart is supposed to work, but we can imagine > feeding all these files with all the object ids just before restart and

Building on my own experience with zap I envision the restart operation of a given task occurring in the context of that task. (I assume this is how restart will work). Therefore, it makes much sense that before every syscall that requires a pre-determined resource identifier (eg. clone, ipc, pty allocation), the task will place the desired value in "next\_id" (and that will only be meaningful during restart) and invoke the said syscall. Voila.

Note that the restart will "rebuild" the container's state (and the task state) as it reads in the data from some source. It is likely that not all data will be available when the first said syscall is about to be invoked, so you may not be able to feed everything ahead of time.

```
> let the process pick up the objects ids as it needs them.
> Of course, this would require to enhance the files formats, as well as
> the way things are stored in the task struct.
> Hope what I'm saying is not too stupid ;-)?
> Regards,
> Nadia
>>
>>>
>>>> and why you'd
>>>> want to write multiple identifiers in one go;
>>>
>>>
>>> I used multiple identifiers only for the pid values: this is because
>>> when a new pid value is allocated for a process that belongs to
>>> nested namespaces, the lower level upid nr values are allocated in a
>>> single shot. (see alloc_pid()).
>>>> it seems to complicate the
>>> code and interface with minimal gain.
>>>> In practice, a process will only do either one or the other, so a
>>>> single
>>> file is enough (e.g. "next_id").
>>>> Also, writing a single value at a time followed by the syscall is
>>>> enough;
>>>> it's definitely not a performance issue to have multiple calls.
>>>> We assume the user/caller knows what she's doing, so no need to
>>>> classify
>>>> the identifier (that is, tell the kernel it's a pid, or an ipc id)
>>>> ahead
>>> of time. The caller simply writes a value and then calls the relevant
>>> syscall, or otherwise the results may not be what she expected...
```

```
>>>> If such context is expected to be required (although I don't see any at
>>>> the moment), we can require that the user write "TYPE VALUE" pair to
>>>> the "next_id" file.
>>>
>>>
>>> That's exactly what I wanted to avoid by creating 1 file per object.
>>> Now, it's true that in a restart context where I guess that things
>>> will be done synchronously, we could have a single next_id file.
>>>
>>>>
>>>>
>>>> When one of these files (or both of them) is filled, a structure
>>>> pointed to
>>>> by the calling task struct is filled with these ids.
>>>> Then, when the object is created, the id(s) present in that
>>>> structure are
>>>> used, instead of the default ones.
>>>>
>>>> The patches are against 2.6.25-rc3-mm1, in the following order:
>>>>
>>>> [PATCH 1/4] adds the proofs facility for next ipc to be created.
>>>> [PATCH 2/4] adds the proofs facility for next task to be forked.
>>>> [PATCH 3/4] makes use of the specified id (if any) to allocate the
>>>> new IPC
              object (changes the ipc_addid() path).
>>>>
>>>> [PATCH 4/4] uses the specified id(s) (if any) to set the upid nr(s)
>>>> for a newly
              allocated process (changes the
>>>>
>>>> alloc_pid()/alloc_pidmap() paths).
>>>> Any comment and/or suggestions are welcome.
>>>>
>>>> Cc-ing Pavel and Sukadev, since they are the pid namespace authors.
>>>>
>>>> Regards.
>>>> Nadia
>>>>
>>>> --
>>>>
>>>> --
>>>>
>>>>
>>>>
>>>>
>>>
>>>
>>> Regards,
```

```
>>> Nadia
>>
>>
>>
>>
>>
>>
>>
>>

Containers mailing list
Containers@lists.linux-foundation.org
https://lists.linux-foundation.org/mailman/listinfo/containers
```

# Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id Posted by serue on Sun, 16 Mar 2008 03:43:20 GMT

```
Quoting Oren Laadan (orenl@cs.columbia.edu):
>
>
> Nadia Derbey wrote:
> > Oren Laadan wrote:
> >>
> >>
> >> Nadia Derbey wrote:
>>> Oren Laadan wrote:
> >>>
>>>>
>>>>
>>>> Nadia.Derbey@bull.net wrote:
>>>>> A couple of weeks ago, a discussion has started after Pierre's
>>>>> proposal for
>>>>> a new syscall to change an ipc id (see thread
>>>> http://lkml.org/lkml/2008/1/29/209).
>>>>>
> >>>>
>>>> Oren's suggestion was to force an object's id during its creation,
> >>>> rather
>>>>> than 1. create it, 2. change its id.
>>>>> So here is an implementation of what Oren has suggested.
>>>>>
>>>>> 2 new files are defined under /proc/self:
>>>>> . next_ipcid --> next id to use for ipc object creation
>>>>> . next_pids --> next upid nr(s) to use for next task to be forked
                   (see patch #2 for more details).
>>>>>
> >>>
```

```
> >>>
>>>>
>>>> Generally looks good. One meta-comment, though:
>>>> I wonder why you use separate files for separate resources,
> >>>
> >>>
>>>> That would be needed in a situation wheere we don't care about next,
>>> say, ipc id to be created but we need a predefined pid. But I must
>>> admit I don't see any pratical application to it.
> >>
> >>
>>> exactly; why set the next-ipc value so far in advance? I think it's
>>> better (and less confusing) if we require that setting the next-id value
> >> be done right before the respective syscall.
> >
> > Ok, but this "requirement" should be widely agreed upon ;-)
> A discussion on the overall checkpoint/restart policy is certainly due
> (and increasingly noted recently).
>> What I mean here is that the solution with 1 file per "object type" can
> > easily be extended imho:
> I'm aiming at simplicity and minimal (but not restrictive) API for user
> space. I argue that we never really need more than one predetermined value
> at a time (eg see below), and the cost of setting such value is so small
> that there is no real benefit in setting more than one at a time (either
> via multiple files or via an array of values). If in fact you wanted more
> than one type at a time, you could still make it happen with a single
> file without adding many user-visible files in /proc/<pid>.
>
> So far, I can't think of any such identifier that we'd like to pre-set
> that does not fit into a "long" type;
As Nadia has mentioned, if we have checkpointed a container which has
another pid namespace underneath itself, then we will need to restart
```

some tasks with two predetermined pids. So we'll need two (or more) longs for the tasks in deeper namespaces.

```
> simply because the kernel does not
> use such identifiers in the first place (pid, ipc, pty#, vc# .. etc). To
> be on the safe side, we can require that the format be "long VAL", just
> in case (and later you could have other formats).
> The only exception, perhaps, is if a TCP connection is rebuilt with a,
> say, connect() syscall, and some information needs to be "predetermined"
```

> so we'll need to extend the format. That can be done with another type

```
> eg. "tcp ....." or a separate file (per your view), _then_, not now.
> (As a side note, I don't suggest that this is how TCP will be restored).
> In any event, the bottom line is that a single file, with a single
> value at a time (possibly annotated with a type), is the simplest, and
> isn't restrictive, for our purposes. Looking one step ahead, simplicity
> and minimal commitment to user space is important in trying to push this
> to the mainline kernel...
>> I don't know how the restart is supposed to work, but we can imagine
> > feeding all these files with all the object ids just before restart and
> Building on my own experience with zap I envision the restart operation
> of a given task occurring in the context of that task.
Could be, but not necessarily the case. Eric has mentioned using elf
files for restart, and that's one way to go, but whether one central
restart task sets up all the children or the children set themselves up
is yet another design point we haven't decided. I would think that
with a centralized restart it would be easier to assure for instance
that shared anon pages would be properly set up and shared, but since
you advocate each-task-starts-itself I trust zap must handle that.
> (I assume this is
> how restart will work). Therefore, it makes much sense that before every
> syscall that requires a pre-determined resource identifier (eg. clone,
> ipc, pty allocation), the task will place the desired value in "next_id"
> (and that will only be meaningful during restart) and invoke the said
> syscall. Voila.
> Note that the restart will "rebuild" the container's state (and the task
> state) as it reads in the data from some source. It is likely that not
> all data will be available when the first said syscall is about to be
> invoked, so you may not be able to feed everything ahead of time.
>
>> let the process pick up the objects ids as it needs them.
>> Of course, this would require to enhance the files formats, as well as
>> the way things are stored in the task struct.
> > Hope what I'm saying is not too stupid ;-)?
> > Regards.
> > Nadia
```

> > > >> > >>>

>>>> and why you'd

```
>>>> want to write multiple identifiers in one go;
> >>>
> >>>
>>>> I used multiple identifiers only for the pid values: this is because
>>>> when a new pid value is allocated for a process that belongs to
>>>> nested namespaces, the lower level upid nr values are allocated in a
>>> single shot. (see alloc_pid()).
> >>>
>>>> it seems to complicate the
>>>> code and interface with minimal gain.
>>>> In practice, a process will only do either one or the other, so a
>>>> single
>>>> file is enough (e.g. "next_id").
>>>> Also, writing a single value at a time followed by the syscall is
>>>> enough;
>>>> it's definitely not a performance issue to have multiple calls.
>>>> We assume the user/caller knows what she's doing, so no need to
>>>> classify
>>>> the identifier (that is, tell the kernel it's a pid, or an ipc id)
> >>> ahead
>>>> of time. The caller simply writes a value and then calls the relevant
>>>> syscall, or otherwise the results may not be what she expected...
>>>> If such context is expected to be required (although I don't see any at
>>>> the moment), we can require that the user write "TYPE VALUE" pair to
>>>> the "next id" file.
> >>>
> >>>
>>>> That's exactly what I wanted to avoid by creating 1 file per object.
>>>> Now, it's true that in a restart context where I guess that things
>>>> will be done synchronously, we could have a single next id file.
> >>>
> >>>
>>>>>
>>>>> When one of these files (or both of them) is filled, a structure
>>>>> pointed to
>>>>> by the calling task struct is filled with these ids.
>>>>> Then, when the object is created, the id(s) present in that
>>>>> structure are
>>>>> used, instead of the default ones.
>>>>>
>>>>> The patches are against 2.6.25-rc3-mm1, in the following order:
>>>>>
>>>>> [PATCH 1/4] adds the procfs facility for next ipc to be created.
>>>>> [PATCH 2/4] adds the proofs facility for next task to be forked.
>>>>> [PATCH 3/4] makes use of the specified id (if any) to allocate the
> >>> new IPC
                object (changes the ipc_addid() path).
> >>>>
```

```
>>>>> [PATCH 4/4] uses the specified id(s) (if any) to set the upid nr(s)
>>>>> for a newly
               allocated process (changes the
>>>>>
>>>>> alloc_pid()/alloc_pidmap() paths).
> >>>>
>>>>> Any comment and/or suggestions are welcome.
>>>>> Cc-ing Pavel and Sukadev, since they are the pid namespace authors.
>>>>>
>>>>> Regards,
>>>>> Nadia
>>>>>
>>>>> --
>>>>>
> >>>> --
>>>>
>>>>
> >>>
>>>>
> >>>
> >>>
>>>> Regards,
> >>> Nadia
> >>
> >>
> >>
> >
> >
> Containers mailing list
> Containers@lists.linux-foundation.org
> https://lists.linux-foundation.org/mailman/listinfo/containers
Containers mailing list
Containers@lists.linux-foundation.org
https://lists.linux-foundation.org/mailman/listinfo/containers
```

Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id Posted by Oren Laadan on Sun, 16 Mar 2008 19:08:44 GMT View Forum Message <> Reply to Message

Serge E. Hallyn wrote:
> Quoting Oren Laadan (orenl@cs.columbia.edu):
>>
>> Nadia Derbey wrote:
>>> Oren Laadan wrote:
>>>>

```
>>>> Nadia Derbey wrote:
>>>>
>>>> Oren Laadan wrote:
>>>>
>>>>>
>>>> Nadia.Derbey@bull.net wrote:
>>>>>
>>>>> A couple of weeks ago, a discussion has started after Pierre's
>>>>> proposal for
>>>>> a new syscall to change an ipc id (see thread
>>>>> http://lkml.org/lkml/2008/1/29/209).
>>>>>>
>>>>>
>>>>> Oren's suggestion was to force an object's id during its creation,
>>>>> rather
>>>>> than 1. create it, 2. change its id.
>>>>>
>>>>> So here is an implementation of what Oren has suggested.
>>>>>
>>>>> 2 new files are defined under /proc/self:
>>>>> . next ipcid --> next id to use for ipc object creation
>>>>> . next pids --> next upid nr(s) to use for next task to be forked
                    (see patch #2 for more details).
>>>>>
>>>>>
>>>>>
>>>> Generally looks good. One meta-comment, though:
>>>>>
>>>>> I wonder why you use separate files for separate resources,
>>>>
>>>> That would be needed in a situation wheere we don't care about next,
>>>> say, ipc id to be created but we need a predefined pid. But I must
>>>> admit I don't see any pratical application to it.
>>>>
>>> exactly; why set the next-ipc value so far in advance? I think it's
>>>> better (and less confusing) if we require that setting the next-id value
>>> be done right before the respective syscall.
>>> Ok, but this "requirement" should be widely agreed upon ;-)
>> A discussion on the overall checkpoint/restart policy is certainly due
>> (and increasingly noted recently).
>>> What I mean here is that the solution with 1 file per "object type" can
>>> easily be extended imho:
>> I'm aiming at simplicity and minimal (but not restrictive) API for user
>> space. I argue that we never really need more than one predetermined value
>> at a time (eg see below), and the cost of setting such value is so small
>> that there is no real benefit in setting more than one at a time (either
>> via multiple files or via an array of values). If in fact you wanted more
>> than one type at a time, you could still make it happen with a single
```

>> file without adding many user-visible files in /proc/<pid>. >> >> So far, I can't think of any such identifier that we'd like to pre-set >> that does not fit into a "long" type; > As Nadia has mentioned, if we have checkpointed a container which has > another pid namespace underneath itself, then we will need to restart > some tasks with two predetermined pids. So we'll need two (or more) > longs for the tasks in deeper namespaces. I see. So more than a single "long" type is probably needed. I'd still prefer that the "scope" of a preset identifier through "next id" should be the subsequent syscall; so if you need multiple values for the next syscall you use it, but you don't support leftovers for the next syscall to use. The typing system can be something like "long VAL" and then for array "long\* VAL VAL VAL ...", for instance. >> simply because the kernel does not >> use such identifiers in the first place (pid, ipc, pty#, vc# .. etc). To >> be on the safe side, we can require that the format be "long VAL", just >> in case (and later you could have other formats). >> >> The only exception, perhaps, is if a TCP connection is rebuilt with a, >> say, connect() syscall, and some information needs to be "predetermined" >> so we'll need to extend the format. That can be done with another type >> eg. "tcp ....." or a separate file (per your view), \_then\_, not now. >> (As a side note, I don't suggest that this is how TCP will be restored). >> >> In any event, the bottom line is that a single file, with a single >> value at a time (possibly annotated with a type), is the simplest, and >> isn't restrictive, for our purposes. Looking one step ahead, simplicity >> and minimal commitment to user space is important in trying to push this >> to the mainline kernel... >> >>> I don't know how the restart is supposed to work, but we can imagine >>> feeding all these files with all the object ids just before restart and >> Building on my own experience with zap I envision the restart operation >> of a given task occurring in the context of that task. > Could be, but not necessarily the case. Eric has mentioned using elf

I'm not familiar with the details of this.

restart task sets up all the children or the children set themselves up
 is yet another design point we haven't decided. I would think that
 with a centralized restart it would be easier to assure for instance

> files for restart, and that's one way to go, but whether one central

> that shared anon pages would be properly set up and shared, but since > you advocate each-task-starts-itself I trust zap must handle that.

The main reason I think a task should setup itself, is because most of the setup requires that new resources be allocated, and the kernel is already centered around this approach that a task allocates for itself, not for another task. For instance, if you need to restore a VMA, you simply call mmap(), a new file, you call open() etc.

Shared anon pages are one example of shared resources that may be used by multiple processes. Zap's approach is to have the "first" user (in the sense of the first time the resource is seen during checkpoint) do the actual restore, and place it in a global table, and then subsequent tasks will find it in the table and "map" it into their view.

Decentralizing also allow multiple tasks to restart concurrently.

Are we ready to start concrete discussion on the architecture for the checkpoint/restart? (and if so .. time to change the subject line).

```
>
>> (I assume this is
>> how restart will work). Therefore, it makes much sense that before every
>> syscall that requires a pre-determined resource identifier (eg. clone,
>> ipc, pty allocation), the task will place the desired value in "next_id"
>> (and that will only be meaningful during restart) and invoke the said
>> syscall. Voila.
>>
>> Note that the restart will "rebuild" the container's state (and the task
>> state) as it reads in the data from some source. It is likely that not
>> all data will be available when the first said syscall is about to be
>> invoked, so you may not be able to feed everything ahead of time.
>>
>>> let the process pick up the objects ids as it needs them.
>>> Of course, this would require to enhance the files formats, as well as
>>> the way things are stored in the task_struct.
>>>
>>> Hope what I'm saying is not too stupid ;-)?
>>> Regards,
>>> Nadia
>>>>> and why you'd
>>>> want to write multiple identifiers in one go;
>>>> I used multiple identifiers only for the pid values: this is because
>>>> when a new pid value is allocated for a process that belongs to
```

```
>>>> nested namespaces, the lower level upid nr values are allocated in a
>>>> single shot. (see alloc pid()).
>>>>
>>>>> it seems to complicate the
>>>> code and interface with minimal gain.
>>>>> In practice, a process will only do either one or the other, so a
>>>> single
>>>> file is enough (e.g. "next_id").
>>>>> Also, writing a single value at a time followed by the syscall is
>>>> enough;
>>>>> it's definitely not a performance issue to have multiple calls.
>>>>> We assume the user/caller knows what she's doing, so no need to
>>>>> classify
>>>>> the identifier (that is, tell the kernel it's a pid, or an ipc id)
>>>>> ahead
>>>> of time. The caller simply writes a value and then calls the relevant
>>>> syscall, or otherwise the results may not be what she expected...
>>>>> If such context is expected to be required (although I don't see any at
>>>>> the moment), we can require that the user write "TYPE VALUE" pair to
>>>>> the "next id" file.
>>>>
>>>> That's exactly what I wanted to avoid by creating 1 file per object.
>>>> Now, it's true that in a restart context where I guess that things
>>>> will be done synchronously, we could have a single next_id file.
>>>>
>>>>> When one of these files (or both of them) is filled, a structure
>>>>> pointed to
>>>>> by the calling task struct is filled with these ids.
>>>>>
>>>>> Then, when the object is created, the id(s) present in that
>>>>> structure are
>>>>> used, instead of the default ones.
>>>>>
>>>>> The patches are against 2.6.25-rc3-mm1, in the following order:
>>>>>
>>>>> [PATCH 1/4] adds the procfs facility for next ipc to be created.
>>>>> [PATCH 2/4] adds the procfs facility for next task to be forked.
>>>>> [PATCH 3/4] makes use of the specified id (if any) to allocate the
>>>>> new IPC
                object (changes the ipc_addid() path).
>>>>>
>>>>> [PATCH 4/4] uses the specified id(s) (if any) to set the upid nr(s)
>>>>> for a newly
                allocated process (changes the
>>>>>
>>>>> alloc_pid()/alloc_pidmap() paths).
>>>>>
>>>>> Any comment and/or suggestions are welcome.
>>>>>
>>>>> Cc-ing Pavel and Sukadev, since they are the pid namespace authors.
```

```
>>>>>
>>>>> Regards,
>>>>> Nadia
>>>>>
>>>>> --
>>>>>
>>>>> --
>>>>>
>>>>>
>>>>>
>>>>
>>>> Regards,
>>>> Nadia
>>>>
>>>>
>>>
>> Containers mailing list
>> Containers@lists.linux-foundation.org
>> https://lists.linux-foundation.org/mailman/listinfo/containers
Containers mailing list
Containers@lists.linux-foundation.org
```

https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id Posted by serue on Mon, 17 Mar 2008 14:44:52 GMT

```
Quoting Oren Laadan (orenl@cs.columbia.edu):
> Serge E. Hallyn wrote:
>> Quoting Oren Laadan (orenl@cs.columbia.edu):
>>>
>>> Nadia Derbey wrote:
>>> Oren Laadan wrote:
>>>>
>>>> Nadia Derbey wrote:
>>>>
>>>> Oren Laadan wrote:
>>>>>
>>>>>
>>>>> Nadia.Derbey@bull.net wrote:
>>>>>
>>>>> A couple of weeks ago, a discussion has started after Pierre's
>>>>> proposal for
```

```
>>>>> a new syscall to change an ipc id (see thread
>>>>> http://lkml.org/lkml/2008/1/29/209).
>>>>>>
>>>>>>
>>>>> Oren's suggestion was to force an object's id during its creation,
>>>>> rather
>>>>> than 1. create it, 2. change its id.
>>>>>>
>>>>> So here is an implementation of what Oren has suggested.
>>>>>>
>>>>> 2 new files are defined under /proc/self:
>>>>>> . next ipcid --> next id to use for ipc object creation
>>>>> . next_pids --> next upid nr(s) to use for next task to be forked
                     (see patch #2 for more details).
>>>>>>
>>>>>
>>>>>
>>>>> Generally looks good. One meta-comment, though:
>>>>>
>>>>> I wonder why you use separate files for separate resources,
>>>>>
>>>> That would be needed in a situation wheere we don't care about next,
>>>>> say, ipc id to be created but we need a predefined pid. But I must
>>>> admit I don't see any pratical application to it.
>>>>
>>>> exactly; why set the next-ipc value so far in advance? I think it's
>>>> better (and less confusing) if we require that setting the next-id
>>>> value
>>>> be done right before the respective syscall.
>>> Ok, but this "requirement" should be widely agreed upon ;-)
>>> A discussion on the overall checkpoint/restart policy is certainly due
>>> (and increasingly noted recently).
>>>
>>>> What I mean here is that the solution with 1 file per "object type" can
>>> easily be extended imho:
>>> I'm aiming at simplicity and minimal (but not restrictive) API for user
>>> space. I argue that we never really need more than one predetermined
>>> value
>>> at a time (eg see below), and the cost of setting such value is so small
>>> that there is no real benefit in setting more than one at a time (either
>>> via multiple files or via an array of values). If in fact you wanted more
>>> than one type at a time, you could still make it happen with a single
>>> file without adding many user-visible files in /proc/<pid>.
>>>
>>> So far, I can't think of any such identifier that we'd like to pre-set
>>> that does not fit into a "long" type:
>> As Nadia has mentioned, if we have checkpointed a container which has
>> another pid namespace underneath itself, then we will need to restart
>> some tasks with two predetermined pids. So we'll need two (or more)
```

>> longs for the tasks in deeper namespaces. > I see. So more than a single "long" type is probably needed. I'd still > prefer that the "scope" of a preset identifier through "next\_id" should > be the subsequent syscall: > so if you need multiple values for the next > syscall you use it, but you don't support leftovers for the next syscall > to use. Agreed. > The typing system can be something like "long VAL" and then for > array "long\* VAL VAL VAL ...", for instance. >>> simply because the kernel does not >>> use such identifiers in the first place (pid, ipc, ptv#, vc# .. etc). To >>> be on the safe side, we can require that the format be "long VAL", just >>> in case (and later you could have other formats). >>> >>> The only exception, perhaps, is if a TCP connection is rebuilt with a, >>> say, connect() syscall, and some information needs to be "predetermined" >>> so we'll need to extend the format. That can be done with another type >>> eg. "tcp ....." or a separate file (per your view), \_then\_, not now. >>> (As a side note, I don't suggest that this is how TCP will be restored). >>> >>> In any event, the bottom line is that a single file, with a single >>> value at a time (possibly annotated with a type), is the simplest, and >>> isn't restrictive, for our purposes. Looking one step ahead, simplicity >>> and minimal commitment to user space is important in trying to push this >>> to the mainline kernel.... >>> >>> I don't know how the restart is supposed to work, but we can imagine >>>> feeding all these files with all the object ids just before restart and >>> Building on my own experience with zap I envision the restart operation >>> of a given task occurring in the context of that task. >> Could be, but not necessarily the case. Eric has mentioned using elf >> files for restart, and that's one way to go, but whether one central

> I'm not familiar with the details of this.

Well he wasn't specific and I'm not sure what his details were, I just pictured it the way crack and other userspace c/r systems have worked, where the checkpoint creates and ELF which you execute to restart the task(set).

>> restart task sets up all the children or the children set themselves up >> is yet another design point we haven't decided. I would think that

- >> with a centralized restart it would be easier to assure for instance
- >> that shared anon pages would be properly set up and shared, but since
- >> you advocate each-task-starts-itself I trust zap must handle that.

>

- > The main reason I think a task should setup itself, is because most of
- > the setup requires that new resources be allocated, and the kernel is
- > already centered around this approach that a task allocates for itself,
- > not for another task. For instance, if you need to restore a VMA, you
- > simply call mmap(), a new file, you call open() etc.

Agreed, it does seem cleaner, and if we go with the "sys\_create\_id()" approach then clearly that's where we're aiming.

- > Shared anon pages are one example of shared resources that may be used
- > by multiple processes. Zap's approach is to have the "first" user (in
- > the sense of the first time the resource is seen during checkpoint) do
- > the actual restore, and place it in a global table, and then subsequent
- > tasks will find it in the table and "map" it into their view.

Makes sense.

> Decentralizing also allow multiple tasks to restart concurrently.

Yes, but we lose that if we force create\_with\_pid() to be implemented by setting /proc/sys/whatever/pid\_min and max :)

- > Are we ready to start concrete discussion on the architecture for the
- > checkpoint/restart ? (and if so .. time to change the subject line).

Good news on this topic - unofficial word is that the containers mini-summit at OLS has been approved. They don't yet know whether it will be monday or tuesday, but hopefully this is enough information early enough for anyone needing to make/change travel plans.

thanks, -serge

>>> (I assume this is

- >>> how restart will work). Therefore, it makes much sense that before every
- >>> syscall that requires a pre-determined resource identifier (eg. clone,
- >>> ipc, pty allocation), the task will place the desired value in "next id"
- >>> (and that will only be meaningful during restart) and invoke the said
- >>> syscall. Voila.

>>>

- >>> Note that the restart will "rebuild" the container's state (and the task
- >>> state) as it reads in the data from some source. It is likely that not
- >>> all data will be available when the first said syscall is about to be
- >>> invoked, so you may not be able to feed everything ahead of time.

```
>>>
>>>
>>>> let the process pick up the objects ids as it needs them.
>>>> Of course, this would require to enhance the files formats, as well as
>>>> the way things are stored in the task_struct.
>>>>
>>>> Hope what I'm saying is not too stupid ;-)?
>>>>
>>>> Regards,
>>>> Nadia
>>>>
>>>>> and why you'd
>>>>> want to write multiple identifiers in one go;
>>>>>
>>>>> I used multiple identifiers only for the pid values: this is because
>>>>> when a new pid value is allocated for a process that belongs to nested
>>>> namespaces, the lower level upid nr values are allocated in a single
>>>> shot. (see alloc_pid()).
>>>>>
>>>>> it seems to complicate the
>>>>> code and interface with minimal gain.
>>>>> In practice, a process will only do either one or the other, so a
>>>>> single
>>>>> file is enough (e.g. "next_id").
>>>>> Also, writing a single value at a time followed by the syscall is
>>>>> enough:
>>>>> it's definitely not a performance issue to have multiple calls.
>>>>> We assume the user/caller knows what she's doing, so no need to
>>>>> classify
>>>>> the identifier (that is, tell the kernel it's a pid, or an ipc id)
>>>>> ahead
>>>>> of time. The caller simply writes a value and then calls the relevant
>>>>> syscall, or otherwise the results may not be what she expected...
>>>>> If such context is expected to be required (although I don't see any
>>>>> at
>>>>> the moment), we can require that the user write "TYPE VALUE" pair to
>>>>> the "next_id" file.
>>>>>
>>>>> That's exactly what I wanted to avoid by creating 1 file per object.
>>>> Now, it's true that in a restart context where I guess that things
>>>> will be done synchronously, we could have a single next id file.
>>>>>
>>>>> When one of these files (or both of them) is filled, a structure
>>>>> pointed to
>>>>> by the calling task struct is filled with these ids.
>>>>>>
>>>>> Then, when the object is created, the id(s) present in that
>>>>> structure are
```

```
>>>>> used, instead of the default ones.
>>>>>>
>>>>> The patches are against 2.6.25-rc3-mm1, in the following order:
>>>>>>
>>>>> [PATCH 1/4] adds the proofs facility for next ipc to be created.
>>>>> [PATCH 2/4] adds the proofs facility for next task to be forked.
>>>>> [PATCH 3/4] makes use of the specified id (if any) to allocate the
>>>>> new IPC
                object (changes the ipc_addid() path).
>>>>>>
>>>>> [PATCH 4/4] uses the specified id(s) (if any) to set the upid nr(s)
>>>>> for a newly
                allocated process (changes the
>>>>>>
>>>>> alloc_pid()/alloc_pidmap() paths).
>>>>>>
>>>>> Any comment and/or suggestions are welcome.
>>>>>>
>>>>> Cc-ing Pavel and Sukadev, since they are the pid namespace authors.
>>>>>>
>>>>> Regards,
>>>>> Nadia
>>>>>>
>>>>> --
>>>>>>
>>>>> --
>>>>>
>>>>>>
>>>>>
>>>>>
>>>>> Regards,
>>>>> Nadia
>>>>
>>>>
>>>>
>>> Containers mailing list
>>> Containers@lists.linux-foundation.org
>>> https://lists.linux-foundation.org/mailman/listinfo/containers
Containers mailing list
Containers@lists.linux-foundation.org
https://lists.linux-foundation.org/mailman/listinfo/containers
```

Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id Posted by Nadia Derbey on Tue, 15 Apr 2008 10:30:26 GMT

View Forum Message <> Reply to Message

Nick Andrew wrote:

> On Fri, Apr 04, 2008 at 04:51:29PM +0200, Nadia.Derbey@bull.net wrote: . echo "LONG XX" > /proc/self/next\_id >> next object to be created will have an id set to XX . echo "LONG<n> X0 ... X<n-1>" > /proc/self/next\_id >> next object to be created will have its ids set to XX0, ... X<n-1> >> This is particularly useful for processes that may have several ids if >> they belong to nested namespaces. >> > > How do you handle race conditions, i.e. you specify the ID for the > next object to be created, and then some other thread goes and creates > an object before your thread creates one? > Nick.

Sorry for not answering earlier, I just saw your e-mail!

It's true that the way I've done things, the "create\_with\_id" doesn't take into account multi-threaded apps, since "self" is related to the thread group leader.

May be using something like /proc/self/task/<my\_tid>/next\_id would be better, but I have to think more about it...

Regards, Nadia

\_\_\_\_\_

Containers mailing list Containers@lists.linux-foundation.org https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id Posted by Oren Laadan on Tue, 15 Apr 2008 18:52:33 GMT

```
Nadia Derbey wrote:

> Nick Andrew wrote:

>> On Fri, Apr 04, 2008 at 04:51:29PM +0200, Nadia.Derbey@bull.net wrote:

>>

>> . echo "LONG XX" > /proc/self/next_id

>>> next object to be created will have an id set to XX

>>> . echo "LONG
>> . echo "LONG
>>> . mext object to be created will have its ids set to XX0, ... X
>>> . This is particularly useful for processes that may have several

>>> ids if
```

they belong to nested namespaces. >> >> >> How do you handle race conditions, i.e. you specify the ID for the >> next object to be created, and then some other thread goes and creates >> an object before your thread creates one? >> >> Nick. > > Sorry for not answering earlier, I just saw your e-mail! [I too managed to miss that message]. > It's true that the way I've done things, the "create\_with\_id" doesn't > take into account multi-threaded apps, since "self" is related to the > thread group leader. > May be using something like /proc/self/task/<my\_tid>/next\_id would be > better, but I have to think more about it... That /proc/self links to /proc/TGID slipped my mind. Definitely must be done on a per-thread basis (and /proc/<TGID>/task/<PID>/next id will do the trick). Oren. > Regards, > Nadia Containers mailing list Containers@lists.linux-foundation.org https://lists.linux-foundation.org/mailman/listinfo/containers

Subject: Re: [RFC][PATCH 0/4] Object creation with a specified id Posted by Nadia Derbey on Fri, 18 Apr 2008 05:46:29 GMT

View Forum Message <> Reply to Message

#### Nick Andrew wrote:

> On Fri, Apr 04, 2008 at 04:51:29PM +0200, Nadia.Derbey@bull.net wrote:
>
>> . echo "LONG XX" > /proc/self/next\_id
>> next object to be created will have an id set to XX
>> . echo "LONG
>> . echo "LONG
>> /proc/self/next\_id

>> next object to be created will have its ids set to XX0, ... X<n-1>

>>	This is particularly useful for processes that may have several ids if	
>>	they belong to nested namespaces.	
>		
>		
	ow do you handle race conditions, i.e. you specify the ID for the	
> next object to be created, and then some other thread goes and creates		
> an object before your thread creates one?		
>		
> Ni	ck.	
OK,	race problem between threads is fixed. Thanks for finding the issue!	
<b>T</b>		
rne	new patch series is coming next.	

Regards, Nadia

\_\_\_\_

Containers mailing list Containers@lists.linux-foundation.org https://lists.linux-foundation.org/mailman/listinfo/containers