Subject: Re: [PATCH 8/16] Masquerade the siginfo when sending a pid to a foreign namespace

Posted by Pavel Emelianov on Tue, 10 Jul 2007 06:56:14 GMT

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sukadev@us.ibm.com wrote:

- > Pavel Emelianov [xemul@openvz.org] wrote:
- > | When user send signal from (say) init namespace to any task in a sub
- > I namespace the siginfo struct must not carry the sender's pid value, as
- > I this value may refer to some task in the destination namespace and thus
- > | may confuse the application.

- > Also, do you prevent signals to the child reaper of a container from within
- > its container? If so, can you show me where you handle it? I can't
- > seem to find it.

>

- > And I guess you do allow signals to the child-reaper of a container from
- > its parent container.

See my comment below.

```
> |
> | The consensus was to pretend in this case as if it is the kernel who
> | sends the signal.
> |
> | The pid_ns_accessible() call is introduced to check this pid-to-ns
  accessibility.
>
>
> | Signed-off-by: Pavel Emelianov <xemul@openvz.org>
>
> | ---
> |
   include/linux/pid.h | 10 +++++++
   kernel/signal.c
                   2 files changed, 38 insertions(+), 6 deletions(-)
>
> | diff -upr linux-2.6.22-rc4-mm2.orig/include/linux/pid.h
linux-2.6.22-rc4-mm2-2/include/linux/pid.h
> | --- linux-2.6.22-rc4-mm2.orig/include/linux/pid.h 2007-06-14 12:14:29.000000000 +0400
> | +++ linux-2.6.22-rc4-mm2-2/include/linux/pid.h 2007-07-04 19:00:38.000000000 +0400
> | @ @ -83,6 +89,16 @ @ extern void FASTCALL(detach pid(struct t
> return nr;
> | }
> |
> | + * checks whether the pid actually lives in the namespace ns, i.e. it was
> | + * created in this namespace or it was moved there.
> | + */
```

```
> | +
> | +static inline int pid_ns_accessible(struct pid_namespace *ns, struct pid *pid)
> | + return pid->numbers[pid->level].ns == ns;
> | +}
> | +
> | #define do_each_pid_task(pid, type, task) \
> | do {
> | struct hlist node *pos ; \
> | diff -upr linux-2.6.22-rc4-mm2.orig/kernel/signal.c linux-2.6.22-rc4-mm2-2/kernel/signal.c
> | --- linux-2.6.22-rc4-mm2.orig/kernel/signal.c 2007-07-04 19:00:38.000000000 +0400
> | +++ linux-2.6.22-rc4-mm2-2/kernel/signal.c 2007-07-04 19:00:38.000000000 +0400
> | @ @ -1124,13 +1124,31 @ @ EXPORT_SYMBOL_GPL(kill_pid_info_as_uid);
> | * is probably wrong. Should make it like BSD or SYSV.
    */
> |
> |
> | -static int kill something info(int sig, struct siginfo *info, int pid)
> | +static inline void masquerade_siginfo(struct pid_namespace *src_ns,
> | + struct pid *tgt_pid, struct siginfo *info)
> | + if (tgt_pid != NULL && !pid_ns_accessible(src_ns, tgt_pid)) {
> | + /*
> | + * current namespace is not seen from the taks we
> | + * want to send the signal to, so pretend as if it
> | + * is the kernel who does this to avoid pid messing
> | + * by the target
> | + */
> | +
> | + info->si pid = 0;
> | + info->si_code = SI_KERNEL;
> | + }
> | +}
> | +static int kill_something_info(int sig, struct siginfo *info, int pid nr)
> | {
> | int ret;
> | + struct pid *pid;
> | +
> | rcu_read_lock();
> | - if (!pid) {
> | + if (!pid nr) {
> | ret = kill_pgrp_info(sig, info, task_pgrp(current));
> | - } else if (pid == -1) {
> | + } else if (pid_nr == -1) {
> int retval = 0, count = 0;
     struct task_struct * p;
> So what happens if we run "kill -s <sig> -1" from within a container?
```

> Do you terminate all processes in the system or just the process in > the container?

That's the biggest problem in the whole set. I do not allow for any signal to the namespaces init (and use "standart" init in my experiences), since I have no ideas of how to make it look good.

Checking for abilities in the sys_kill() is a solution, but why wasn't it such in the global init case? Why init checks for signals in get_signal_to_deliver(). I have to think a bit more with this place. Maybe checking for permissions in sys_kill is a good solution.

On of the ideas I had is that the namespace's init has to accept all the signals with si_code == SI_KERNEL (this will include signals from parent namespaces as well), but the problem is that struct siginfo's do not reach the get_signal_to_deliver in 100% times. If we just could somehow push the siginfo to init, I would concern the problem to be solved.

Thanks, Pavel

> -

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