
Subject: Add documentation for the RSS controller
Posted by [Balbir Singh](#) on Tue, 12 Jun 2007 06:57:21 GMT
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Here's the latest version of the RSS documentation patch. The RSS code has several useful comments in it, it is advised to read the comments and this documentation.

Please report any errors, mistakes, spelling or grammatical errors

Changelog (v2)

1. Incorporate comments from Pavel

Signed-off-by: Balbir Singh <balbir@linux.vnet.ibm.com>

Documentation/controller/rss.txt | 177 +++++
1 file changed, 177 insertions(+)

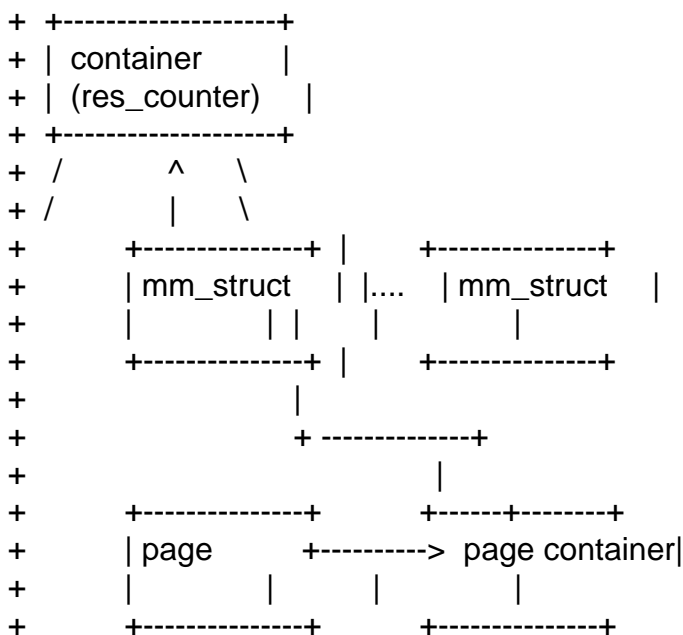
```
diff -puN /dev/null Documentation/controller/rss.txt
--- /dev/null 2007-06-01 20:42:04.000000000 +0530
+++ linux-2.6.22-rc24-mm2-balbir/Documentation/controller/rss.txt 2007-06-12
12:23:58.000000000 +0530
@@ -0,0 +1,177 @@
+RSS (Resident Set Size) controller
+
+1. History
+
+The RSS controller has a long history. A request for comments for the memory
+controller was posted by Balbir Singh [1]. At the time the RFC was posted
+there were several implementations for memory control, the goal of the
+RFC was to build consensus and agreement for the minimal features required
+for memory control. The first RSS controller was posted by Balbir Singh[2]
+in Feb 2007. Pavel Emelianov [3][4][5] has since posted three versions of the
+RSS controller. The latest version works on top of v10 of the containers
+patches [6].
+
+2. Memory Control
+
+Memory is a unique resource in the sense that it is present in a limited
+amount. If a task requires a lot of CPU processing, the task can spread
+its processing over a period of hours, days, months or years, but with
+memory, the same physical memory needs to be reused to accomplish the task.
+
+The memory controller implementation has been divided into phases, these
+are
```

- +1. RSS controller
- +2. Page Cache controller
- +3. mlock(2) controller
- +4. Kernel user memory accounting and slab control
- +5. user mappings length controller
- +
- +The RSS controller is the first controller developed, the page cache controller
- +is under development [7].

+2.1. Design

- +
- +The core of the design is a counter called the res_counter. The res_counter
- +tracks the current RSS usage and limit of the group of processes associated
- +with the controller. A res_counter is embedded in the mm_struct of a process
- +and within the container that groups processes together. Each container
- +has a RSS specific data structure (rss_container) associated with it.

+2.2. Accounting



(Figure 1: Hierarchy of Accounting)

- +Figure 1 shows the important aspects of the controller
- +
- +1. Accounting happens per container
- +2. Each mm_struct knows about which container they belong to
- +3. Each page has a pointer to the page_container, which in turn knows the
- + container it belongs to
- +
- +The accounting is done currently in two phases. In the first phase

+container_rss_prepare() is invoked to setup the necessary data structures
+and check if the container that is being charged is over its limit. If
+it is then reclaim is invoked on the container. More details can be found
+in the reclaim section of this document. If everything goes well, a page
+meta-data-structure called page_container is allocated and associated
+with the page.
+
+In the second phase, container_rss_add is invoked from page_add_*_rmap().
+This routine adds the page to the per container LRU.

+2.3 Shared Page Accounting

+
+Shared pages are accounted on the basis of the first touch approach. The
+container that first touches a page is accounted for the page. The principle
+behind this approach is that a container that aggressively uses a shared
+page, will eventually get charged for it (once it is uncharged from
+the container that brought it in -- this will happen on memory pressure).

+2.4 Reclaim

+
+Each container maintains a per container LRU that consists of an active
+and inactive list. When a container goes over its limit, we first try
+and reclaim memory from the container so as to make space for the new
+pages that the container has touched. If the reclaim is unsuccessful,
+an OOM routine is invoked to select and kill the bulkiest task in the
+container.

+
+The reclaim algorithm has not been modified for containers, except that
+pages that are selected for reclaiming come from the per container LRU
+list (through isolate_pages_in_container())

+3. User Interface

+
+(From Pavel's posting)

+
+1. Prepare the containers
+# mkdir -p /containers/rss
+# mount -t container none /containers/rss -o rss

+
+2. Make the new group and move bash into it
+# mkdir /containers/rss/0
+# echo \$\$ > /containers/rss/0/tasks

+
+Since now we're in the 0 container.
+We can alter the RSS limit
+# echo -n 6000 > /containers/rss/0/rss_limit

+
+We can check the usage

+# cat /containers/rss/0/rss_usage

+25

+

+The rss_failcnt gives the number of times that the container limit was exceeded and the rss_reclaimed gives the count of the number of times reclaim was called.

+

+4. Testing

+

+Balbir posted Imbench [8] and AIM9 [9] results for the RSS v2[4] patches.

+Apart from that v2 has been tested with several applications for the OLS paper on memory control. These applications include web servers and database servers. RSS v2 has also been tested on the PPC64, x86_64 and UML platforms.

+

+4.1 Troubleshooting

+

+Sometimes a user might find that the application under a container is terminated, there are several causes for this

+

+1. The container limit is too low (just too low to do anything useful)

+2. The user is using anonymous memory and swap is turned off or too low

+

+5. TODO

+

+1. Test v3 on more platforms and run more tests

+2. Add support for accounting huge pages (as a separate controller)

+3. Improve the user interface to accept/display memory limits in KB or MB

+ rather than pages (since page sizes can differ across platforms/machines).

+4. Make container lists per-zone

+5. Make per-container scanner reclaim not-shared pages first

+6. Teach controller to account for shared-pages

+7. Start reclamation when the limit is lowered

+8. Start reclamation in the background when the limit is

+ not yet hit but the usage is getting closer

+

+Summary

+

+Overall, the RSS controller has been a stable controller and has been commented and discussed on quite extensively in the community.

+

+References

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+1. Singh, Balbir. RFC: Memory Controller, <http://lwn.net/Articles/206697/>

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+ <http://lwn.net/Articles/222762/>

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+ <http://lkml.org/lkml/2007/3/6/198>

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- + <http://lkml.org/lkml/2007/4/9/74>
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- +8. Singh, Balbir. RSS controller V2 test results (lmbench),
- + <http://lkml.org/lkml/2007/5/17/232>
- +9. Singh, Balbir. RSS controller V2 AIM9 results
- + <http://lkml.org/lkml/2007/5/18/1>

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