Subject: Re: [PATCH 11/15] Signal semantics Posted by Pavel Emelianov on Fri, 27 Jul 2007 13:38:19 GMT View Forum Message <> Reply to Message

Oleg Nesterov wrote:

> Damn. I don't have time to read these patches today (will try tomorrow),

Oh, that's OK. I was about to send the set to Andrew only the next week.

This patch is the most strange one and is to be discussed a lot.

We try to do the following two things:

- 1. signals going from the namespace, that the target task doesn't see must be seen as SI_KERNEL if siginfo is allocated;
- 2. signals to init of any namespace must be allowed to send from one of the parent namespaces only. From child namespace, init needs only those, that it's ready to handle (SIGCHLD).

As far as I understand Suka's approach (it's his patch, so I may be not 100% correct - it's better to wait for his comments) he is trying to carry the information about the signal up to the get_signal_to_deliver().

As far as the first issue is concerned, the solution is obvious - all the "calculations" can be done at the beginning of sending the signal, but the second issue is a bit more complicated and I have no good ideas of how to solve this :(yet.

Thanks, Pavel

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> but when I glanced at this patch yesterday I had some suspicions...
> On 07/26, Pavel Emelyanov wrote:
>> +++ linux-2.6.23-rc1-mm1-7/kernel/signal.c 2007-07-26
>> 16:36:37.000000000 +0400
>> @ @ -323,6 +325,9 @ @ static int collect_signal(int sig, struc
>> if (first) {
>> list_del_init(&first->list);
>> copy siginfo(info, &first->info);
>> + if (first->flags & SIGQUEUE CINIT)
>> + kinfo->flags |= KERN_SIGINFO_CINIT;
>> +
>>
>> [...snip...]
>>
>> @ @ -1852,7 +1950,7 @ @ relock:
    * within that pid space. It can of course get signals from
```

```
* its parent pid space.
>>
>> - if (current == task_child_reaper(current))
>> + if (kinfo.flags & KERN_SIGINFO_CINIT)
   continue;
> I think the whole idea is broken, it assumes the sender put something into
> "struct sigqueue".
Yup. That's the problem. It seems to me that the only way to handle init's
signals is to check for permissions in the sending path.
> Suppose that /sbin/init has no handler for (say) SIGTERM, and we send this
> signal from the same namespace. send_signal() sets SIGQUEUE_CINIT, but it
> is lost because __group_complete_signal() silently "converts" sig_fatal()
> signals to SIGKILL using sigaddset().
>> +static void encode_sender_info(struct task_struct *t, struct sigqueue *q)
>> +{
>> + /*
>> + * If sender (i.e 'current') and receiver have the same active
>> + * pid namespace and the receiver is the container-init, set the
>> + * SIGQUEUE_CINIT flag. This tells the container-init that the
>> + * signal originated in its own namespace and so it can choose
>> + * to ignore the signal.
>> + *
>> + * If the receiver is the container-init of a pid namespace,
>> + * but the sender is from an ancestor pid namespace, the
>> + * container-init cannot ignore the signal. So clear the
>> + * SIGQUEUE_CINIT flag in this case.
>> + *
>> + * Also, if the sender does not have a pid_t in the receiver's
>> + * active pid namespace, set si_pid to 0 and pretend it originated
>> + * from the kernel.
>> + */
>> + if (pid ns equal(t)) {
>> + if (is_container_init(t)) {
>> + q->flags |= SIGQUEUE CINIT;
> Ironically, this change carefully preserves the bug we already have :)
>
> This doesn't protect init from "bad" signal if we send it to sub-thread
> of init. Actually, this make the behaviour a bit worse compared to what
> we currently have. Currently, at least the main init's thread survives
> if we send SIGKILL to sub-thread.
>> static int send signal(int sig, struct siginfo *info, struct task struct *t,
```

struct sigpending *signals)

```
>> {
>> @ @ -710,6 +781,7 @ @ static int send signal(int sig, struct s
     copy_siginfo(&q->info, info);
     break;
>> }
>> + encode_sender_info(t, q);
> We still send the signal if __sigqueue_alloc() fails. In that case, the
> dequeued siginfo won't have SIGQUEUE CINIT/KERN SIGINFO CINIT, not good.
>
>> @ @ -1158,6 +1232,13 @ @ static int kill_something_info(int sig,
>>
>> read_lock(&tasklist_lock);
>> for_each_process(p) {
>> + /*
       * System-wide signals apply only to the sender's
       * pid namespace, unless issued from init pid ns.
>> + if (!task_visible_in_pid_ns(p, my_ns))
      continue;
>> +
>> +
    if (p->pid > 1 && p->tgid != current->tgid) {
> This "p->pid > 1" check should die.
>> +static int deny_signal_to_container_init(struct task_struct *tsk, int sig)
>> +{
>> + /*
>> + * If receiver is the container-init of sender and signal is SIGKILL
>> + * reject it right-away. If signal is any other one, let the container
>> + * init decide (in get signal to deliver()) whether to handle it or
>> + * ignore it.
>> + */
>> + if (is_container_init(tsk) && (sig == SIGKILL) && pid_ns_equal(tsk))
>> + return -EPERM;
>> +
>> + return 0;
>> +}
>> +
>> /*
>> * Bad permissions for sending the signal
>> */
>> @ @ -545,6 +584,10 @ @ static int check_kill_permission(int sig
      && !capable(CAP_KILL))
    return error;
>>
>> + error = deny signal to container init(t, sig);
>> + if (error)
```

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>> + return error;
> Hm. Could you explain this change? Why do we need a special check for SIGKILL?
>
>
> (What about ptrace_attach() btw? If it is possible to send a signal to init
> from the "parent" namespace, perhaps it makes sense to allow ptracing as
> well).
```

ptracing of tasks fro different namespaces is not possible at all, since strace utility determines the fork()-ed child pid from the parent's eax register, which would contain the pid value as this parent sees his child. But if the strace is in different namespace - it won't be able to find this child with the pid value from parent's eax.

Maybe it's worth disabling cross-namespaces ptracing...

```
> Oleg.
>
```