Subject: Re: [PATCH 0/13] Pid namespaces (OpenVZ view) Posted by serue on Fri, 25 May 2007 14:25:50 GMT View Forum Message <> Reply to Message Quoting Pavel Emelianov (xemul@openvz.org): > Serge E. Hallyn wrote: > Quoting Pavel Emelianov (xemul@openvz.org): > Serge E. Hallyn wrote: > >> Quoting Pavel Emelianov (xemul@openvz.org): > >> Serge E. Hallyn wrote: > >> Quoting Eric W. Biederman (ebiederm@xmission.com): > >> "Serge E. Hallyn" <serue@us.ibm.com> writes: > >> > >> "Serge E. Hallyn" <serue@us.ibm.com> writes: > >> > >> >> one need to save the virtual pid and let global one change;

- >>>>> with Suka's logic this is not clear how to migrate the level
- >>>>> 2 namespace (concerning init to be level 0).
- >>>>> This is a very good point.
- >>>>>
- >>>>> How *would* we migrate the pids at the second level?
- >>>> As long as you don't try and restore pids into the initial pid namespace
- >>>> it isn't a problem. You just record the pid hierarchy and the pid
- >>>> for a task in that hierarchy. There really is nothing special going on
- >>>> that should make migration hard.
- > >>>
- >>>> Or did I miss something?
- >>>> Hmm, no, i guess you are right. I was thinking that getting the pid for
- >>>> a process would be done purely from userspace, but I guess along with a
- >>>> kernel helper to *set* pids, we could also have a kernel helper to get
- >>> all pids for all pid namespaces "above" that of the process doing the
- >>>> checkpoint.
- >>> So do you agree that if we migrate a VS we need to migrate the whole VS?
- >> I started to respond, then realized you were probably asking something
- >> different than I thought. My original response is below, but here is I
- > > think the answer to your question, which is important because I think
- > > your question might highlight a misunderstanding about the design of
- > > Suka's code.
- > >
- >> Let's say a vserver is started, and in there a pidns is started for a
- >> checkpoint/restart job. So let's say we have PID 13 in the root
- > > namespace starting PID 14 in a new namespace. So using (pid, pid ns) as
- > the terminology, we havd (13,1) as the parent process, and (14,1)=(1,2)
- >> as the init of the vserver. Let's ignore other tasks inthe vserver, and
- > > just talk about (1402,2) as the init of the checkpoint restart job, so
- > it is (1402,2)=(1,3). And oh, yeah, (1402,2)=(1,3)=(2309,1).
- > Oh, this is heavy... Lets draw some diagrams.
- > You have a vserver with a namespace in it with a cpt job in it,

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> just like this:
> [node. pids look like (N)]
  `- [vserver. pids look like (N,V)]
       `- [cpt job. pids look like (N,V,P)]
> Is that OK?
It's different from the notation I was using.
Let's stick to calling every process by a full "upid", i.e.
(pid, pid namespace #) because while it's longer it gives more
information.
> We have task in "node" with pid (13) which spawns the task with
> pid (14,1) into the "vserver", like this:
>
> (13)
> `- (14.1)
> If so, then what the notion (14,1)=(1,2) mean?
It means that (pid 14, pid_ns 1) = (pid 1, pid_ns 2). It describes one
task, which in pid namespace 1 is known by pid 14, and in pid namespace
2 is known by pid 1.
(I see the repetative low numbers were confusing...)
> As far as the "cpt job" is concerned we have smth like this:
>
> (13)
> `- (14,1)
       -(1402,2,1)
>
> where (1402,2,1) is the root of the "cpt job", right?
Sure, and in my notation this would be
 [(13,1)]
    ·- [(14,1)(1,2)]
```

Again each level is just one task, but known by several pids.

So coming back to the idea of checkpoint all of pid_ns=2, we would be checkpointing both task [(14,1)(1,2)] and task [(2309,1)(1402,2)(1,3)]. And my question had been how would we access and store the fact that the third task has pid (1,3), which we MUST store and reset, because that is

`- [(2309,1)(1402,2)(1,3)]

that task's active pid namespace, meaning it only knows itself as (1,3).

The task in pid namespace 2 which is doing the checkpointing generally only knows the third task as (1402,2), so we need to provide a mechanism for it to dump all pids in "higher" pid namespaces.

Note that, of course, pids in "lower" pid namespaces can be randomly set. If we are restarting pid namespace 2 on a new system, it's perfectly ok for the pids to look like:

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[(467,1)]
    `- [(5597,1)(1,2)]
      ·- [(5598,1)(1402,2)(1,3)]
Heh, or even
  [(14,1)(467,2)]
    `- [(444,1)(5597,2)(1,3)]
      `- [(445,1)(5598,2)(1402,3)(1,4)]
thanks,
-serge
>> Now when we want to migrate the vserver, a task in pid_ns 2 will look
> > for all tasks with pids in pidns 2. That will automatically include all
> > tasks in pid_ns 3. I think you thought I was asking how we would
> > include pid_ns 3, and are asking whether it would be ok to not migrate
>> pid ns 3? (answer: it's irrelevant, all tasks in pid ns 3 are also in
> pid ns 2 - and in pid ns 1).
> >
>> What I was actually asking was, in the same situation, how would the
>> task in pid ns 2 doing the checkpoint get the pids in pid ns 3. So it
>> sees the task as (1402,2), but needs to also store (1,3) and, on
> > restart, recreate a task with both those pids.
> >
>> But I guess it will be pretty simple, and fall into place once we get
> > c/r semantics started.
> >
> > thanks,
> > -serge
> >
>> [ original response ]
>> I think that's the reasonable thing for people to do, but I don't think
>> we should force them to. I.e. there is no reason you shouldn't be able
> > to take one or two tasks out of a pidns and checkpoint them, and restart
>> them elsewhere. If it turns out they were talking to a third process
> > which wasn't checkpointed, well, too bad.
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>>
>> What you are more likely to need is a new clean set of namespaces to
>> restart in, but again I don't think we should enforce that. So whatever
>> mechanism we end up doing to implementing "clone_with_pid()", we should
>> handle -EBUSY correctly.
>>
>> Anyway, why do you ask? (How does it follow from the conversation?)
>>
>> I wasn't suggesting that it would be ok to only dump part of the pid
>> information, rather I was asking how we would do it correctly :)
>>
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