## Subject: Re: [ckrm-tech] [RFC][PATCH][2/4] Add RSS accounting and control Posted by Balbir Singh on Mon, 19 Feb 2007 14:10:06 GMT

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## Paul Menage wrote:

- > On 2/19/07, Balbir Singh <balbir@in.ibm.com> wrote:
- >>> More worrisome is the potential for use-after-free. What prevents the
- >>> pointer at mm->container from referring to freed memory after we're dropped
- >>> the lock?
- >>>
- >> The container cannot be freed unless all tasks holding references to it are >> gone,
- >
- > ... or have been moved to other containers. If you're not holding
- > task->alloc\_lock or one of the container mutexes, there's nothing to
- > stop the task being moved to another container, and the container
- > being deleted.

>

- > If you're in an RCU section then you can guarantee that the container
- > (that you originally read from the task) and its subsystems at least
- > won't be deleted while you're accessing them, but for accounting like
- > this I suspect that's not enough, since you need to be adding to the
- > accounting stats on the correct container. I think you'll need to hold
- > mm->container\_lock for the duration of memctl\_update\_rss()
- >
- > Paul

>

Yes, that sounds like the correct thing to do.

--

Warm Regards, Balbir Singh